

ETH 263-2210-00L COMPUTER ARCHITECTURE, FALL 2020
HW 4: MEMORY INTERFERENCE AND QoS, MEMORY SCHEDULING,
MEMORY CONTROLLER, EMERGING MEMORY TECHNOLOGIES

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Given: Thursday, Nov 20, 2020

Due: **Thursday, Dec 4, 2020**

- **Handin - Critical Paper Reviews (1).** You need to submit your reviews to <https://safari.ethz.ch/review/architecture20/>. Please check your inbox. You should have received an email with the password you should use to login. If you did not receive any emails, contact comparch@lists.inf.ethz.ch. In the first page after login, you should click in "Computer Architecture Home", and then go to "any submitted paper" to see the list of papers.
- **Handin - Questions (2-8).** You should upload your answers to the Moodle Platform (<https://moodle-app2.1et.ethz.ch/course/view.php?id=13549>) as a single PDF file.

1. Critical Paper Reviews [500 points]

Please read the guidelines for reviewing papers and check the sample reviews. We also assign you a **required reading** for this homework. You may access them by *simply clicking on the QR codes below or scanning them*. We will give out extra credit that is worth 0.5% of your total grade for each good review. If you review a paper other than the REQUIRED papers, you will receive 250 BONUS points on top of 500 points you may get from paper reviews (i.e., each additional submission is worth 250 BONUS points with a possibility to get up to 3000 points).



Guidelines



Sample reviews



Required Reading 1



Required Reading 2

Write an approximately one-page critical review for the following required readings (i.e., Paper #1, and Paper #2) and earn *bonus* points for the remaining 8 papers (i.e., papers from #3 to #10). A review with bullet point style is more appreciated. Try not to use very long sentences and paragraphs. Keep your writing and sentences simple. Make your points bullet by bullet, as much as possible.

1. (REQUIRED) B. C. Lee, E. Ipek, O. Mutlu, and D. Burger, "Architecting Phase Change Memory as a Scalable DRAM Alternative", in ISCA 2009. https://people.inf.ethz.ch/omutlu/pub/pcm_isca09.pdf
2. (REQUIRED) O. Mutlu and T. Moscibroda, "Parallelism-Aware Batch Scheduling: Enhancing both Performance and Fairness of Shared DRAM Systems", in ISCA 2008. https://people.inf.ethz.ch/omutlu/pub/parbs_isca08.pdf
3. E. Ipek, O. Mutlu, J. F. Martínez, and R. Caruana, "Self Optimizing Memory Controllers: A Reinforcement Learning Approach" in ISCA 2008. https://people.inf.ethz.ch/omutlu/pub/rllmc_isca08.pdf
4. Y. Kim, D. Han, O. Mutlu, and M. Harchol-Balter, "ATLAS: A scalable and high-performance scheduling algorithm for multiple memory controllers" in HPCA 2010. https://people.inf.ethz.ch/omutlu/pub/atlas_hPCA10.pdf
5. L. Subramanian, D. Lee, V. Seshadri, H. Rastogi, and O. Mutlu, "BLISS: Balancing performance, fairness and complexity in memory access scheduling" in TPDS 2016. https://people.inf.ethz.ch/omutlu/pub/bliss-memory-scheduler_ieee-tpds16.pdf

6. M. Patel, J. S. Kim, T. Shahroodi, H. Hassan, and O. Mutlu, “*Bit-Exact ECC Recovery (BEER): Determining DRAM On-Die ECC Functions by Exploiting DRAM Data Retention Characteristics*”, in MICRO, 2020 https://people.inf.ethz.ch/omutlu/pub/BEER-bit-exact-ECC-recovery_micro20.pdf
7. N. Hajinazar, P. Patel, M. Patel, K. Kanellopoulos, S. Ghose, R. Ausavarungnirun, G. F. de Oliveira Jr., J. Appavoo, V. Seshadri, and O. Mutlu, “*The Virtual Block Interface: A Flexible Alternative to the Conventional Virtual Memory Framework*” in ISCA 2020. https://people.inf.ethz.ch/omutlu/pub/VBI-virtual-block-interface_isca20.pdf
8. Y. Kim, W. Yang, and O. Mutlu, “*Ramulator: A Fast and Extensible DRAM Simulator*” in CAL 2015. https://people.inf.ethz.ch/omutlu/pub/ramulator_dram_simulator-ieee-cal15.pdf
9. H. Yoon, J. Meza, R. Ausavarungnirun, R. Harding, and O. Mutlu, “*Row Buffer Locality Aware Caching Policies for Hybrid Memories*” in ICCD 2012. https://people.inf.ethz.ch/omutlu/pub/rowbuffer-aware-caching_iccd12.pdf
10. M. K. Qureshi, V. Srinivasan, and J. A. Rivers, “*Scalable high performance main memory system using phase-change memory technology*” in ISCA 2009. <https://dl.acm.org/doi/pdf/10.1145/1555754.1555760>
11. Kültürsay E, Kandemir M, Sivasubramaniam A, Mutlu O, “*Evaluating STT-RAM as an energy-efficient main memory alternative*” in ISPASS 2013. https://people.inf.ethz.ch/omutlu/pub/sttram_ispass13.pdf
12. L. Subramanian, V. Seshadri, A. Ghosh, S. Khan, and O. Mutlu, “*The Application Slowdown Model: Quantifying and Controlling the Impact of Inter-Application Interference at Shared Caches and Main Memory*” in MICRO 2015. https://people.inf.ethz.ch/omutlu/pub/application-slowdown-model_micro15.pdf
13. E. Ebrahimi, C. J. Lee, O. Mutlu, and Y. N. Patt, “*Fairness via Source Throttling: A Configurable and High-Performance Fairness Substrate for Multi-Core Memory Systems,*” in ASPLOS 2010. https://people.inf.ethz.ch/omutlu/pub/fairness-via-throttling_acm_tocs12.pdf
14. S.P. Muralidhara, L. Subramanian, O. Mutlu, M. Kandemir, T. Moscibroda, “*Reducing Memory Interference in Multicore Systems via Application-aware Memory Channel Partitioning,*” MICRO 2011. <https://people.inf.ethz.ch/omutlu/pub/memory-channel-partitioning-micro11.pdf>

2. Memory System [200 points]

A machine with a 4 GB DRAM main memory system has 4 channels, 1 rank per channel and 4 banks per rank. The cache block size is 64 bytes.

(a) You are given the following byte addresses and the channel and bank to which they are mapped:

Byte: $0x0000 \Rightarrow$ Channel 0, Bank 0
Byte: $0x0100 \Rightarrow$ Channel 0, Bank 0
Byte: $0x0200 \Rightarrow$ Channel 0, Bank 0
Byte: $0x0400 \Rightarrow$ Channel 1, Bank 0
Byte: $0x0800 \Rightarrow$ Channel 2, Bank 0
Byte: $0x0C00 \Rightarrow$ Channel 3, Bank 0
Byte: $0x1000 \Rightarrow$ Channel 0, Bank 1
Byte: $0x2000 \Rightarrow$ Channel 0, Bank 2
Byte: $0x3000 \Rightarrow$ Channel 0, Bank 3

Determine which bits of the address are used for each of the following address components. Assume row bits are higher order than column bits:

- Byte on bus
Addr [2 : 0]
 - Channel bits (channel bits are contiguous)
Addr [___ : ___]
 - Bank bits (bank bits are contiguous)
Addr [___ : ___]
 - Column bits (column bits are contiguous)
Addr [___ : ___]
 - Row bits (row bits are contiguous)
Addr [___ : ___]
- (b) Two applications App 1 and App 2 share this memory system (using the address mapping scheme you determined in part (a)). The memory scheduling policy employed is FR-FCFS. The following requests are queued at the memory controller request buffer at time t . Assume the first request (A) is the oldest and the last one (A + 15) is the youngest.

A B A + 1 A + 2 A + 3 B + 10 A + 4 B + 12 A + 5 A + 6 A + 7
A + 8 A + 9 A + 10 A + 11 A + 12 A + 13 A + 14 A + 15

These are cache block addresses, not byte addresses. Note that requests to $A + x$ are from App 1, while requests to $B + x$ are from App 2. Addresses A and B are row-aligned (i.e., they are at the start of a row) and are at the same bank but are in different rows.

Assuming row-buffer hits take T time units to service and row-buffer conflicts/misses take 2T time units to service, what is the slowdown (compared to when run alone on the same system) of

- App 1?

- App 2?

(c) Which application slows down more?

Why?

(d) In class, we discussed memory channel partitioning and memory request scheduling as two solutions to mitigate interference and application slowdowns in multicore systems. Propose another solution to reduce the slowdown of the more-slowed-down application, without increasing the slowdown of the other application? Be concrete.

3. DRAM Scheduling and Latency [200 points]

You would like to understand the configuration of the DRAM subsystem of a computer using reverse engineering techniques. Your current knowledge of the particular DRAM subsystem is limited to the following information:

- The physical memory address is 16 bits.
- The DRAM subsystem consists of a single channel, 2 banks, and 64 rows per bank.
- The DRAM is byte-addressable.
- The most-significant bit of the physical memory address determines the bank. The following 6 bits of the physical address determine the row.
- The DRAM command bus operates at 1 GHz frequency.
- The memory controller issues commands to the DRAM in such a way that *no command* for servicing a *later* request is issued before issuing a READ command for the current request, which is the oldest request in the request buffer. For example, if there are requests A and B in the request buffer, where A is the older request and the two requests are to different banks, the memory controller does *not* issue an ACTIVATE command to the bank that B is going to access *before* issuing a READ command to the bank that A is accessing.
- The memory controller services requests in order with respect to each bank. In other words, for a given bank, the memory controller first services the oldest request in the *request buffer* that targets the same bank. If all banks are ready to service a request, the memory controller first services the oldest request in the request buffer.

You realize that you can observe the memory requests that are waiting to be serviced in the request buffer. At a particular point in time, you take the snapshot of the request buffer and you observe the following requests in the request buffer (in descending order of request age, where the oldest request is on the top):

time
↓
Read 0xD780
Read 0x280C
Read 0xE4D0
Read 0x2838

At the same time you take the snapshot of the request buffer, you start probing the DRAM command bus. You observe the DRAM command type and the cycle (relative to the first command) at which the command is seen on the DRAM command bus. The following are the DRAM commands you observe on the DRAM bus while the requests above are serviced.

```
Cycle 0 --- READ
Cycle 1 --- PRECHARGE
Cycle 8 --- PRECHARGE
Cycle 13 --- ACTIVATE
Cycle 18 --- READ
Cycle 20 --- ACTIVATE
Cycle 22 --- READ
Cycle 25 --- READ
```

Answer the following questions using the information provided above.

- (a) What are the following DRAM timing parameters used by the memory controller, in terms of nanoseconds? If there is not enough information to infer the value of a timing parameter, write *unknown*.
- i) ACTIVATE-to-READ latency:

ii) ACTIVATE-to-PRECHARGE latency:

iii) PRECHARGE-to-ACTIVATE latency:

iv) READ-to-PRECHARGE latency:

v) READ-to-READ latency:

(b) What is the status of the banks *prior* to the execution of any of the above requests? In other words, which rows from which banks were open immediately prior to issuing the DRAM commands listed above? Fill in the table below indicating whether a bank has an open row, and if there is an open row, specify its address. If there is not enough information to infer the open row address, write *unknown*.

	Open or Closed?	Open Row Address
Bank 0		
Bank 1		

(c) To improve performance, you decide to implement the idea of Tiered-Latency DRAM (TL-DRAM) in the DRAM chip. Assume that a bank consists of a single subarray. With TL-DRAM, an entire bank is divided into a near segment and far segment. When accessing a row in the near segment, the ACTIVATE-to-READ latency *reduces* by 1 cycle and the ACTIVATE-to-PRECHARGE latency reduces by 3 cycles. When precharging a row in the near segment, the PRECHARGE-to-ACTIVATE latency reduces by 3 cycles. When accessing a row in the far segment, the ACTIVATE-to-READ latency *increases* by 1 cycle and the ACTIVATE-to-PRECHARGE latency increases by 2 cycles. When precharging a row in the far segment, the PRECHARGE-to-ACTIVATE latency increases by 2 cycles. The following table summarizes the changes in the affected latency parameters.

Timing Parameter	Near Segment Latency	Far Segment Latency
ACTIVATE-to-READ	-1	+1
ACTIVATE-to-PRECHARGE	-3	+2
PRECHARGE-to-ACTIVATE	-3	+2

Assume that the rows in the near segment have smaller row ids compared to the rows in the far segment. In other words, physical memory row addresses 0 through $N - 1$ are the near-segment rows, and physical memory row addresses N through 63 are the far-segment rows.

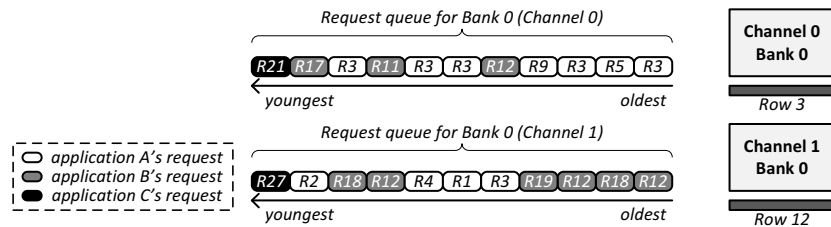
If the above DRAM commands are issued 2 cycles faster with TL-DRAM compared to the baseline (the last command is issued in cycle 23), how many rows are in the near segment, i.e., what is N ? Show your work.

4. Memory Scheduling [200 points]

To serve a memory request, the memory controller issues one or multiple DRAM commands to access data from a bank. There are four different DRAM commands.

- **ACTIVATE:** Loads the row (that needs to be accessed) into the bank's row-buffer. This is called *opening* a row. (**Latency: 15ns**)
- **PRECHARGE:** Restores the contents of the bank's row-buffer back into the row. This is called *closing* a row. (**Latency: 15ns**)
- **READ/WRITE:** Accesses data from the row-buffer. (**Latency: 15ns**)

The following figure shows the snapshot of the memory request buffers (in the memory controller) at t_0 . Each request is color-coded to denote the application to which it belongs (assume that all applications are running on separate cores). Additionally, each request is annotated with the address (or index) of the row that the request needs to access (e.g., $R3$ means that the request is to the 3rd row). Furthermore, assume that all requests are read requests.



A memory request is considered to be *served* when the **READ** command is complete (i.e., 15ns after the request's **READ** command has been issued). In addition, each application (A, B, or C) is considered to be **stalled** until *all* of its memory requests (across all the request buffers) have been served.

Assume that, initially (at t_0) each bank has the 3rd and the 12th row loaded in the row-buffer, respectively. Furthermore, no additional requests from any of the applications arrive at the memory controller.

4.1. Application-Unaware Scheduling Policies

- (a) Using the **FCFS** scheduling policy, what is the **stall time** of each application?

- (b) Using the **FR-FCFS** scheduling policy, what is the stall time of each application?

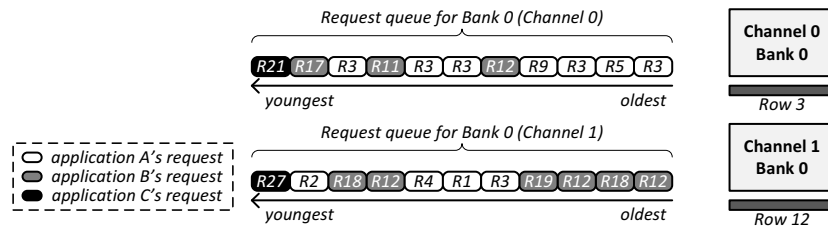
- (c) What property of memory references does the **FR-FCFS** scheduling policy exploit? (Three words or less.)

- (d) Briefly describe the scheduling policy that would **maximize** the *request throughput* at any given bank, where request throughput is defined as the number of requests served per unit amount of time. (Less than 10 words.)

4.2. Application-Aware Scheduling Policies

Of the three applications, application C is the least memory-intensive (i.e., has the lowest number of outstanding requests). However, it experiences the largest stall time since its requests are served only after the numerous requests from other applications are first served. To ensure the shortest stall time for application C, one can assign its requests with the highest priority, while assigning the same low priority to the other two applications (A and B).

- (a) **Scheduling Policy X:** When application C is assigned a high priority and the other two applications are assigned the same low priority, what is the stall time of each application? (Among requests with the same priority, assume that *FR-FCFS* is used to break ties.)



Can you design an even better scheduling policy? While application C now experiences low stall time, you notice that the other two applications (A and B) are still delaying each other.

- (b) Assign priorities to the other two applications such that you minimize the average stall time across all applications. Specifically, list all **three** applications in the order of highest to lowest priority. (Among requests with the same priority, assume that *FR-FCFS* is used to break ties.)

- (c) **Scheduling Policy Y:** Using your new scheduling policy, what is the stall time of each application? (Among requests with the same priority, assume that *FR-FCFS* is used to break ties.)

- (d) Order the four scheduling policies (FCFS, FR-FCFS, X, Y) in the order of lowest to highest average stall time.

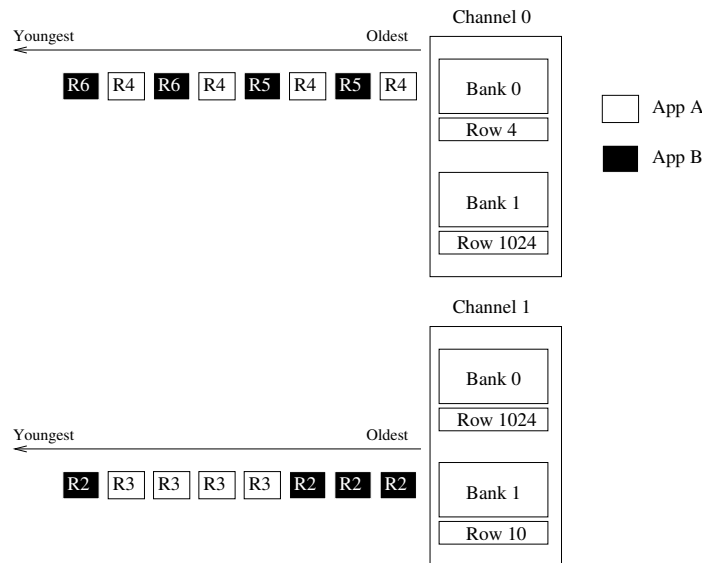
5. Memory Request Scheduling [200 points]

A machine has a DRAM main memory organized as 2 channels, 1 rank and 2 banks/channel. An open row policy is used, i.e., a row is retained in the row-buffer after an access until an access to another row is made. The following commands (defined as we discussed in class) can be issued to DRAM with the given latencies:

- ACTIVATE: 15 ns
- PRECHARGE: 15 ns
- READ/WRITE: 15 ns

Assume the bus latency is 0 cycles.

- (a) We studied Parallelism Aware Batch Scheduling (PAR-BS) in class. We will use a PAR-BS-like scheduler that we will call X. This scheduler operates as follows:
- The scheduler forms request batches consisting of the 4 oldest requests from each application at each bank.
 - At each bank, the scheduler ranks applications based on the number of requests they have outstanding at that bank. Applications with a smaller number of requests outstanding are assigned a higher rank.
 - The scheduler always ranks the application with the oldest request higher in the event of a tie between applications.
 - The scheduler prioritizes the requests of applications based on this ranking (higher ranked applications requests are prioritized over lower ranked applications requests).
 - The scheduler repeats the above steps once all requests in a batch are serviced at all banks.



For the same above buffer state:

What is the stall time of application A using this scheduler?

What is the stall time of application B using this scheduler?

Explain why or why not. Provide the fundamental reason why X does or does not improve system performance over an FR-FCFS scheduler.

- (b) Can you design a better memory scheduler (i.e., one that provides higher system performance) than X? Circle one: **YES** **NO**

If yes, answer the questions below. What modifications would you make to scheduler X to design this better scheduler Y? Explain clearly.

What is the stall time of application A using this scheduler Y?

What is the stall time of application B using this scheduler Y?

- (c) Consider a simple channel partitioning scheme where application A's data is mapped to channel 0 and application B's data is mapped to channel 1. When data is mapped to a different channel, only the channel number changes; the bank number does not change. For instance, requests of application A that were mapped to bank 1 of channel 1 would now be mapped to bank 1 of channel 0. What is the stall time of application A using this channel partitioning mechanism and an FR-FCFS memory scheduler?

What is the stall time of application B using this channel partitioning mechanism and an FR-FCFS memory scheduler?

Explain why channel partitioning does better or worse than scheduler Y.

6. Emerging Memory Technologies [100 points]

Computer scientists at ETH developed a new memory technology, ETH-RAM, which is non-volatile. The access latency of ETH-RAM is close to that of DRAM while it provides higher density compared to the latest DRAM technologies. ETH-RAM has one shortcoming, however: it has limited endurance, i.e., a memory cell stops functioning after 10^6 writes are performed to the cell (known as cell wear-out).

A bright ETH student has built a computer system using 1 GB of ETH-RAM as main memory. ETH-RAM exploits a perfect wear-leveling mechanism, i.e., a mechanism that equally distributes the writes over all of the cells of the main memory.

- (a) This student is worried about the lifetime of the computer system she has built. She executes a test program that runs special instructions to bypass the cache hierarchy and repeatedly writes data into different words until **all** the ETH-RAM cells are worn-out (stop functioning) and the system becomes useless. The student's measurements show that ETH-RAM stops functioning (i.e., all its cells are worn-out) in one year (365 days). Assume the following:
- The processor is in-order and there is no memory-level parallelism.
 - It takes 5 ns to send a memory request from the processor to the memory controller and it takes 28 ns to send the request from the memory controller to ETH-RAM.
 - ETH-RAM is word-addressable. Thus, each write request writes 4 bytes to memory.

What is the write latency of ETH-RAM? Show your work.

- (b) ETH-RAM works in the multi-level cell (MLC) mode in which each memory cell stores 2 bits. The student decides to improve the lifetime of ETH-RAM cells by using the single-level cell (SLC) mode. When ETH-RAM is used in SLC mode, the lifetime of each cell improves by a factor of 10 and the write latency decreases by 70%. What is the lifetime of the system using the SLC mode, if we repeat the experiment in part (a), with everything else remaining the same in the system? Show your work.

7. BossMem [100 points]

A researcher has developed a new type of nonvolatile memory, BossMem. He is considering BossMem as a replacement for DRAM. BossMem is 10x faster (all memory timings are 10x faster) than DRAM, but since BossMem is so fast, it has to frequently power-off to cool down. Overheating is only a function of time, not a function of activity. An idle stick of BossMem has to power-off just as frequently as an active stick. When powered-off, BossMem retains its data, but cannot service requests. Both DRAM and BossMem are banked and otherwise architecturally similar. To the researcher's dismay, he finds that a system with 1GB of DRAM performs considerably better than the same system with 1GB of BossMem.

- (i) What can the researcher change or improve in the core (he can't change BossMem or anything beyond the memory controller) that will make his BossMem perform more favorably compared to DRAM, realizing that he will have to be fair and evaluate DRAM with his enhanced core as well? (15 words or less)

- (ii) A colleague proposes he builds a hybrid memory system, with both DRAM and BossMem. He decides to place data that exhibits low row buffer locality in DRAM and data that exhibits high row buffer locality in BossMem. Assume 50% of requests are row buffer hits. Is this a good or bad idea? Show your work.

- (iii) Now a colleague suggests trying to improve the last-level cache replacement policy in the system with the hybrid memory system. Like before, he wants to improve the performance of this system relative to one that uses just DRAM and he will have to be fair in his evaluation. Can he design a cache replacement policy that makes the hybrid memory system look more favorable? In 15 words or less, justify NO or describe a cache replacement policy that would improve the performance of the hybrid memory system more than it would DRAM.

- (iv) In class we talked about another nonvolatile memory technology, phase-change memory (PCM). Which technology, PCM, BossMem, or DRAM requires the greatest attention to security? What is the vulnerability?

- (v) Which is likely of least concern to a security researcher?