

# Digital Design & Computer Arch.

## Lecture 10a: Instruction Set Architectures II

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ETH Zürich

Spring 2022

25 March 2022

# Assignment: Lecture Video (April 1)

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- Why study computer architecture? Why is it important?
- Future Computing Platforms: Challenges & Opportunities
- **Required Assignment**
  - **Watch one of** Prof. Mutlu's lectures and analyze either (or both)
    - <https://www.youtube.com/watch?v=kgiZISOcGFM> (May 2017)
    - <https://www.youtube.com/watch?v=mskTeNnf-i0> (Feb 2021)
- **Optional Assignment – for 1% extra credit**
  - **Write a 1-page summary** of one of the lectures and email us
    - What are your key takeaways?
    - What did you learn?
    - What did you like or dislike?
    - Submit your summary to [Moodle](#) by April 1

# Extra Assignment: Moore's Law (I)

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- **Paper review**
- G.E. Moore. "Cramming more components onto integrated circuits," Electronics magazine, 1965
  
- **Optional Assignment – for 1% extra credit**
  - **Write a 1-page review**
  - Upload PDF file to Moodle – Deadline: April 7
  
- I strongly recommend that you **follow my guidelines for (paper) review** (see next slide)

# Extra Assignment 2: Moore's Law (II)

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## ■ Guidelines on how to review papers critically

- **Guideline slides:** [pdf](#) [ppt](#)
- **Video:** <https://www.youtube.com/watch?v=tOL6FANAJ8c>
  
- Example reviews on "Main Memory Scaling: Challenges and Solution Directions" ([link to the paper](#))
  - [Review 1](#)
  - [Review 2](#)
  
- Example review on "Staged memory scheduling: Achieving high performance and scalability in heterogeneous systems" ([link to the paper](#))
  - [Review 1](#)

# Agenda for Today & Next Few Lectures

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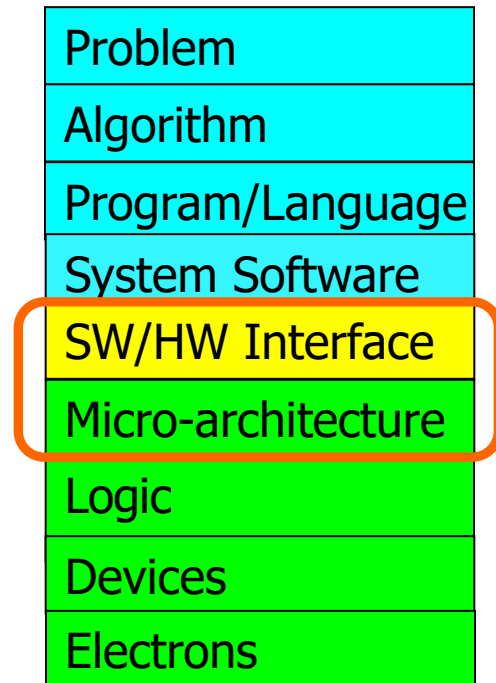
- The von Neumann model
- LC-3: An example of von Neumann machine
- LC-3 and MIPS Instruction Set Architectures
- LC-3 and MIPS assembly and programming
- Introduction to microarchitecture and single-cycle microarchitecture
- Multi-cycle microarchitecture

Problem
Algorithm
Program/Language
System Software
SW/HW Interface
Micro-architecture
Logic
Devices
Electrons

# What Will We Learn Today?

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- Basic elements of a computer & **the von Neumann model**
  - LC-3: An example von Neumann machine
- **Instruction Set Architectures: LC-3 and MIPS**
  - Operate instructions
  - Data movement instructions
  - Control instructions
- **Instruction formats**
- **Addressing modes**



# Readings

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## ■ This week

- Von Neumann Model, ISA, LC-3, and MIPS
  - P&P, Chapters 4, 5 (we will follow these today & tomorrow)
  - H&H, Chapter 6 (until 6.5)
  - P&P, Appendices A and C (ISA and microarchitecture of LC-3)
  - H&H, Appendix B (MIPS instructions)
- Programming
  - P&P, Chapter 6 (we will follow this tomorrow)
- **Recommended:** H&H Chapter 5, especially 5.1, 5.2, 5.4, 5.5

## ■ Next week

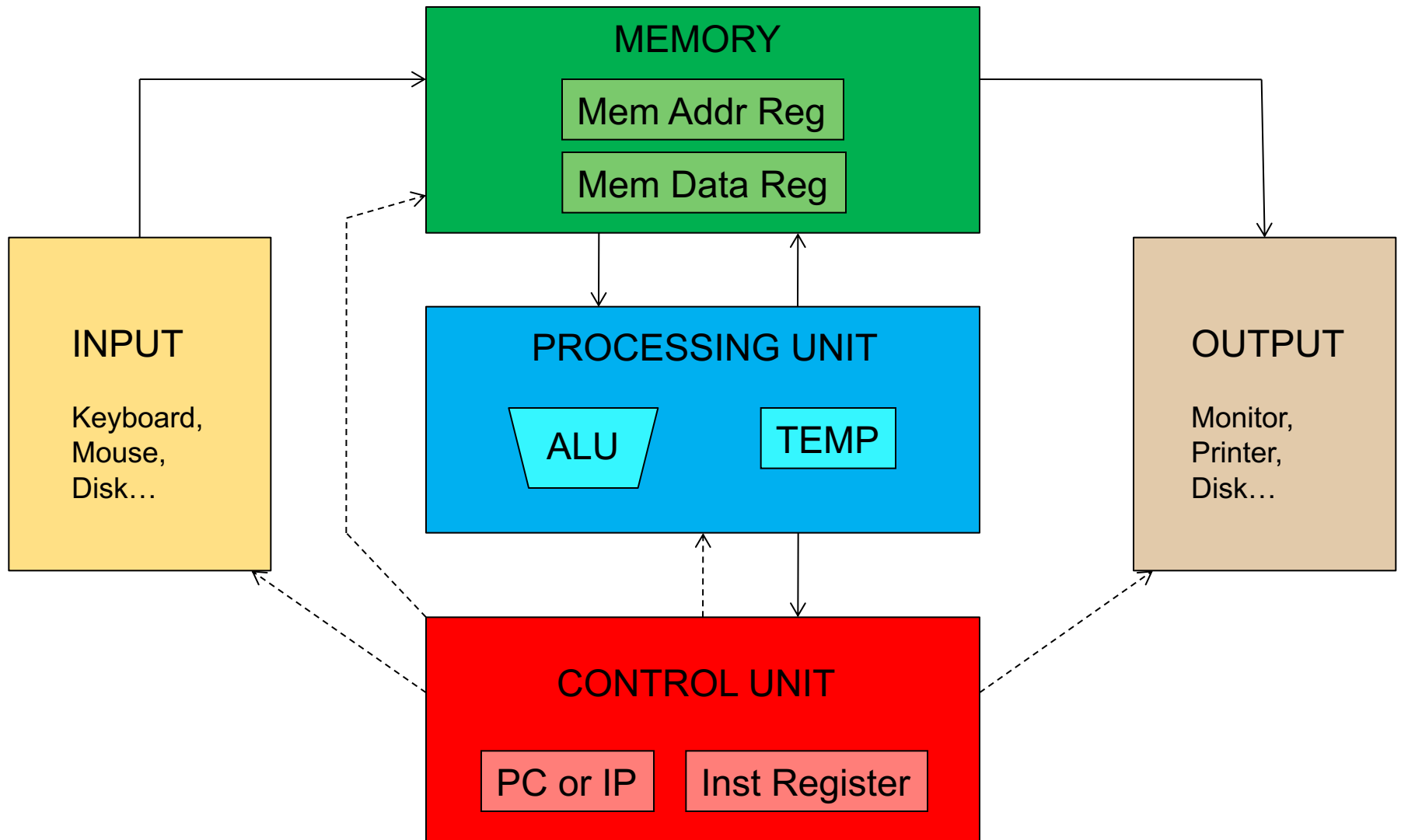
- Introduction to microarchitecture and single-cycle microarchitecture
  - H&H, Chapter 7.1-7.3
  - P&P, Appendices A and C
- Multi-cycle microarchitecture
  - H&H, Chapter 7.4
  - P&P, Appendices A and C

# Quick Review of the von Neumann Model



# Recall: The von Neumann Model

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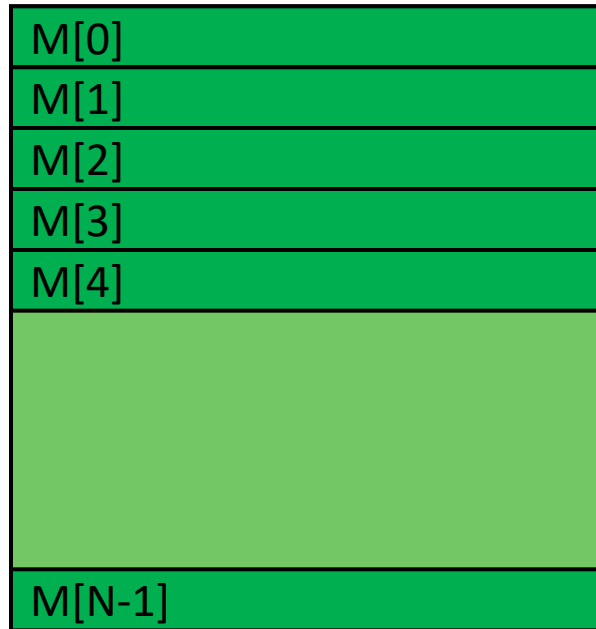
# Recall: von Neumann Model: Two Key Properties

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- Von Neumann model is also called *stored program computer* (instructions in memory). It has two key properties:
- **Stored program**
  - Instructions stored in a linear memory array
  - **Memory is unified** between instructions and data
    - **The interpretation of a stored value depends on the control signals**
- **Sequential instruction processing**
  - One instruction processed (fetched, executed, completed) at a time
  - **Program counter (instruction pointer)** identifies the current instruction
  - **Program counter is advanced sequentially** except for control transfer instructions

# Recall: Programmer Visible (Architectural) State

---



Memory  
array of storage locations  
indexed by an address



Registers

- given special names in the ISA (as opposed to addresses)
- general vs. special purpose



Program Counter

memory address  
of the current (or next) instruction

Instructions (and programs) specify how to transform  
the values of programmer visible state

# Recall: LC-3: A von Neumann Machine

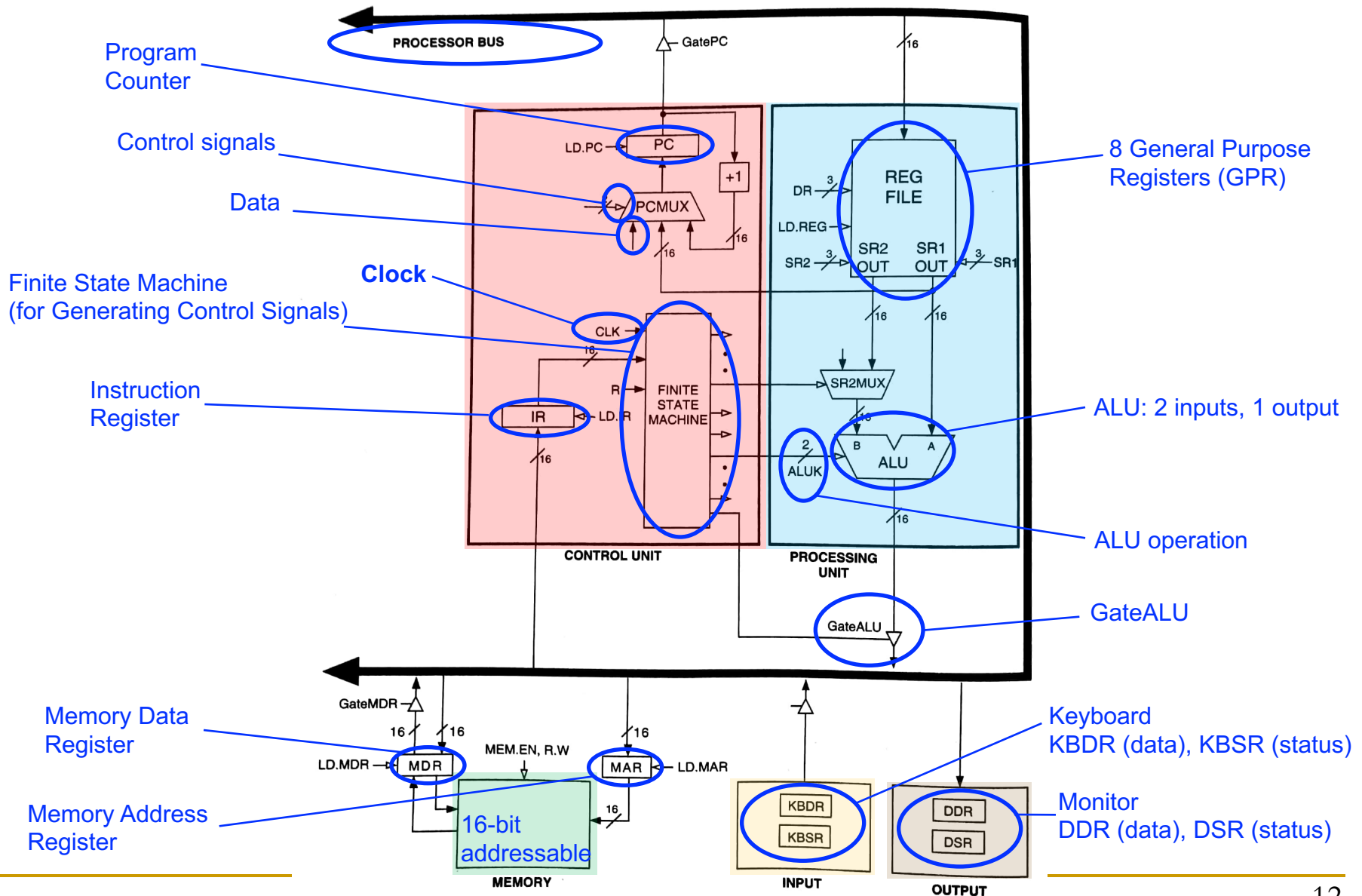
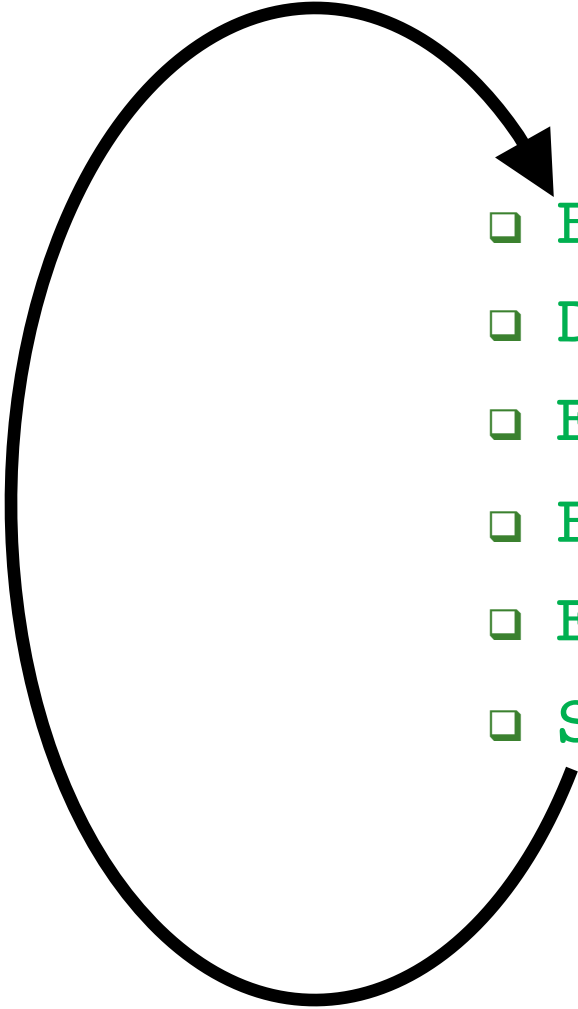


Figure 4.3 The LC-3 as an example of the von Neumann model

# Recall: The Instruction (Processing) Cycle

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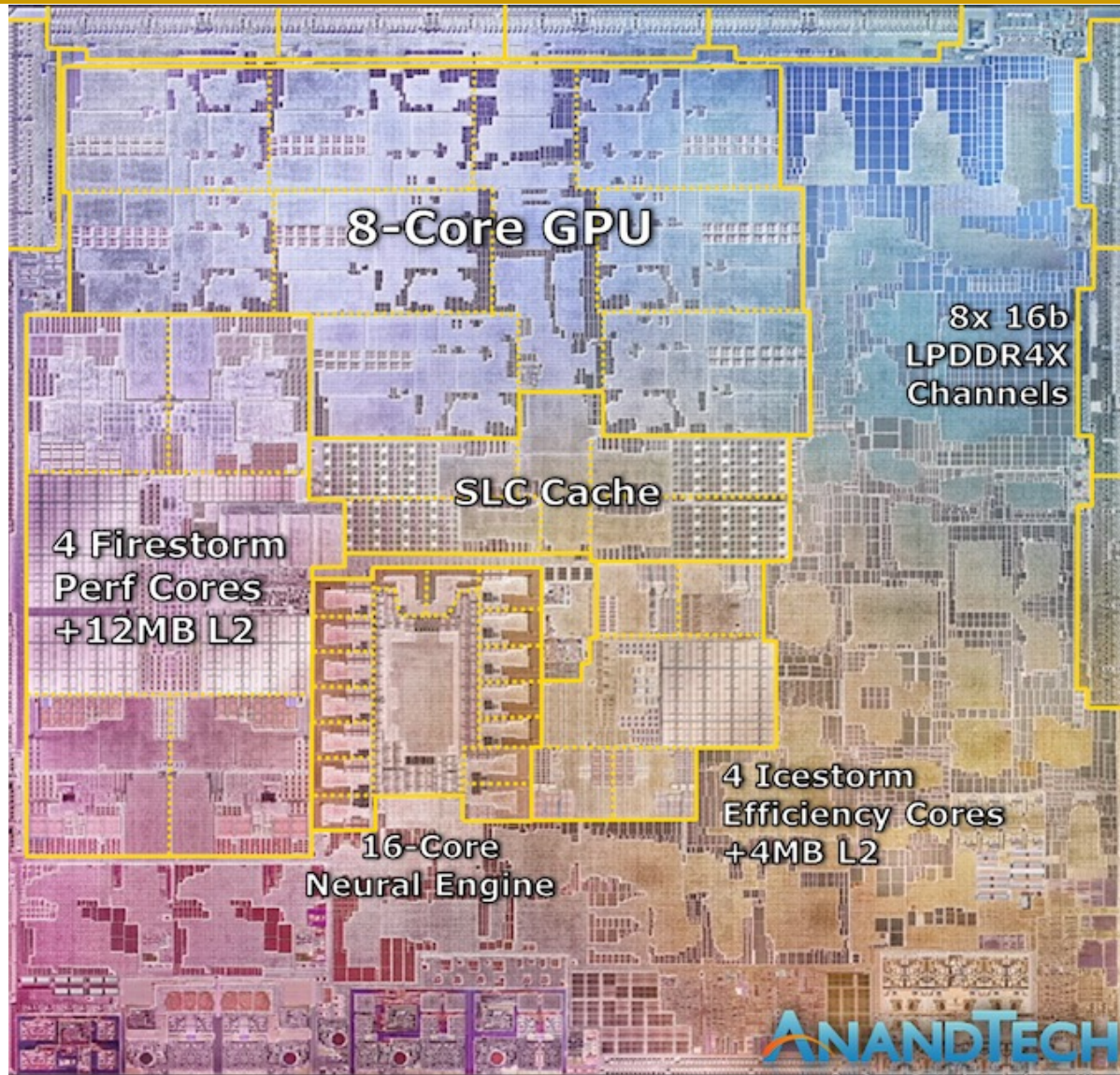
- 
- ❑ FETCH
  - ❑ DECODE
  - ❑ EVALUATE ADDRESS
  - ❑ FETCH OPERANDS
  - ❑ EXECUTE
  - ❑ STORE RESULT

# LC-3: A von Neumann Machine

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# Another von Neumann Machine



Apple M1,  
2021

# Another von Neumann Machine



10nm ESF=Intel 7 Alder Lake die shot (~209mm<sup>2</sup>) from Intel: <https://www.intel.com/content/www/us/en/newsroom/news/12th-gen-core-processors.html>  
Die shot interpretation by Locuza, October 2021

Intel Alder Lake,  
2021





# Another von Neumann Machine



IBM POWER10,  
2020

**Cores:**  
15-16 cores,  
8 threads/core

**L2 Caches:**  
2 MB per core

**L3 Cache:**  
120 MB shared

# LC-3 and MIPS

## Instruction Set Architectures

# The Instruction Set

---

- It defines **opcodes**, **data types**, and **addressing modes**
- ADD and LDR have been our first examples

ADD

OP	DR	SR1			SR2
1	0	1	0	00	2

Register mode

LDR

OP	DR	BaseR	offset6
6	3	0	4

Base+offset mode

# The Instruction Set Architecture

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- The ISA is the **interface between** what the **software** commands and what the **hardware** carries out
- The ISA specifies
  - The **memory organization**
    - Address space (LC-3:  $2^{16}$ , MIPS:  $2^{32}$ )
    - Addressability (LC-3: 16 bits, MIPS: 8 bits)
    - Word- or Byte-addressable
  - The **register set**
    - R0 to R7 in LC-3
    - 32 registers in MIPS
  - The **instruction set**
    - Opcodes
    - Data types
    - Addressing modes
    - Length and format of instructions

Problem
Algorithm
Program
ISA
Microarchitecture
Circuits
Electrons

# Opcodes

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- A large or small **set of opcodes** could be defined
  - E.g, HP Precision Architecture: an instruction for  $A*B+C$
  - E.g, x86 ISA: multimedia extensions (MMX), later SSE and AVX
  - E.g, VAX ISA: opcode to save all information of one program prior to switching to another program
  
- **Tradeoffs** are involved
  - Hardware complexity vs. software complexity
  
- In LC-3 and in MIPS there are three **types of opcodes**
  - Operate
  - Data movement
  - Control

# Opcodes in LC-3

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ADD <sup>+</sup>	0001			DR	SR1	0	00	SR2								
ADD <sup>+</sup>	0001			DR	SR1	1	imm5									
AND <sup>+</sup>	0101			DR	SR1	0	00	SR2								
AND <sup>+</sup>	0101			DR	SR1	1	imm5									
BR	0000			n	z	p	PCoffset9									
JMP	1100			000		BaseR		000000								
JSR	0100			1	PCoffset11											
JSRR	0100			0	00	BaseR		000000								
LD <sup>+</sup>	0010			DR	PCoffset9											
LDI <sup>+</sup>	1010			DR	PCoffset9											
LDR <sup>+</sup>	0110			DR	BaseR		offset6									
LEA <sup>+</sup>	1110			DR	PCoffset9											
NOT <sup>+</sup>	1001			DR	SR	111111										
RET	1100			000		111		000000								
RTI	1000			000000000000												
ST	0011			SR	PCoffset9											
STI	1011			SR	PCoffset9											
STR	0111			SR	BaseR		offset6									
TRAP	1111			0000			trapvect8									
reserved	1101															

Figure 5.3 Formats of the entire LC-3 instruction set. NOTE: + indicates instructions that modify condition codes

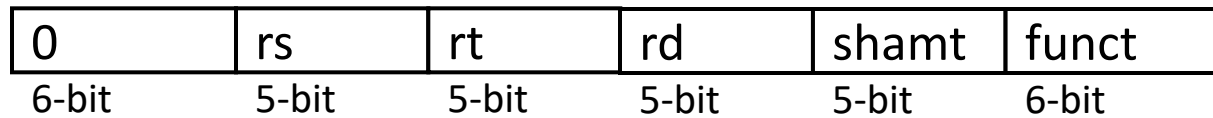
# Opcodes in LC-3b

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ADD <sup>+</sup>	0001				DR			SR1			A	op.spec				
AND <sup>+</sup>	0101				DR			SR1			A	op.spec				
BR	0000				n	z	p	PCoffset9								
JMP	1100				000			BaseR			000000					
JSR(R)	0100				A	operand.specifier										
LDB <sup>+</sup>	0010				DR			BaseR			boffset6					
LDW <sup>+</sup>	0110				DR			BaseR			offset6					
LEA <sup>+</sup>	1110				DR			PCoffset9								
RTI	1000				000000000000											
SHF <sup>+</sup>	1101				DR			SR			A	D	amount4			
STB	0011				SR			BaseR			boffset6					
STW	0111				SR			BaseR			offset6					
TRAP	1111				0000			trapvect8								
XOR <sup>+</sup>	1001				DR			SR1			A	op.spec				
not used	1010															
not used	1011															

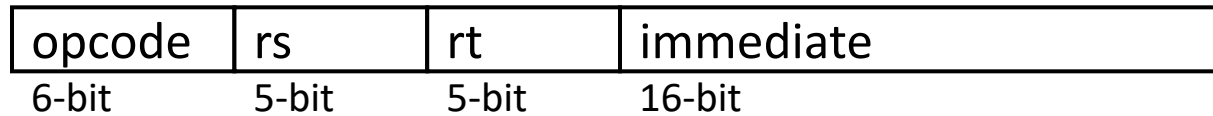


# MIPS Instruction Types

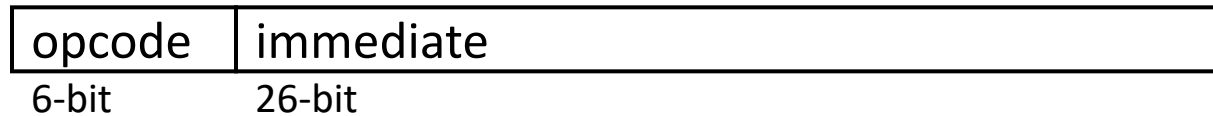
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R-type



I-type



J-type

# Func in MIPS R-Type Instructions (I)

Table B.2 R-type instructions, sorted by funct field

Opcode is 0  
in MIPS R-  
Type  
instructions.  
Func defines  
the operation

Func	Name	Description	Operation
000000 (0)	sll rd, rt, shamt	shift left logical	[rd] = [rt] << shamt
000010 (2)	srl rd, rt, shamt	shift right logical	[rd] = [rt] >> shamt
000011 (3)	sra rd, rt, shamt	shift right arithmetic	[rd] = [rt] >>> shamt
000100 (4)	sllv rd, rt, rs	shift left logical variable	[rd] = [rt] << [rs] <sub>4:0</sub>
000110 (6)	srlv rd, rt, rs	shift right logical variable	[rd] = [rt] >> [rs] <sub>4:0</sub>
000111 (7)	srav rd, rt, rs	shift right arithmetic variable	[rd] = [rt] >>> [rs] <sub>4:0</sub>
001000 (8)	jr rs	jump register	PC = [rs]
001001 (9)	jalr rs	jump and link register	\$ra = PC + 4, PC = [rs]
001100 (12)	syscall	system call	system call exception
001101 (13)	break	break	break exception
010000 (16)	mfhi rd	move from hi	[rd] = [hi]
010001 (17)	mthi rs	move to hi	[hi] = [rs]
010010 (18)	mflo rd	move from lo	[rd] = [lo]
010011 (19)	mtlo rs	move to lo	[lo] = [rs]
011000 (24)	mult rs, rt	multiply	{[hi], [lo]} = [rs] × [rt]
011001 (25)	multu rs, rt	multiply unsigned	{[hi], [lo]} = [rs] × [rt]
011010 (26)	div rs, rt	divide	[lo] = [rs]/[rt], [hi] = [rs]%[rt]
011011 (27)	divu rs, rt	divide unsigned	[lo] = [rs]/[rt], [hi] = [rs]%[rt]

(continued)

# Funcnt in MIPS R-Type Instructions (II)

**Table B.2** R-type instructions, sorted by funct field—Cont'd

Funcnt	Name	Description	Operation
100000 (32)	add rd, rs, rt	add	[rd] = [rs] + [rt]
100001 (33)	addu rd, rs, rt	add unsigned	[rd] = [rs] + [rt]
100010 (34)	sub rd, rs, rt	subtract	[rd] = [rs] - [rt]
100011 (35)	subu rd, rs, rt	subtract unsigned	[rd] = [rs] - [rt]
100100 (36)	and rd, rs, rt	and	[rd] = [rs] & [rt]
100101 (37)	or rd, rs, rt	or	[rd] = [rs]   [rt]
100110 (38)	xor rd, rs, rt	xor	[rd] = [rs] ^ [rt]
100111 (39)	nor rd, rs, rt	nor	[rd] = ~([rs]   [rt])
101010 (42)	slt rd, rs, rt	set less than	[rs] < [rt] ? [rd] = 1 : [rd] = 0
101011 (43)	sltu rd, rs, rt	set less than unsigned	[rs] < [rt] ? [rd] = 1 : [rd] = 0

- Find the complete list of instructions in the H&H Appendix B

# Data Types

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- An ISA supports one or several data types
- LC-3 only supports 2's complement integers
  - Negative of a 2's complement binary value  $X = \text{NOT}(X) + 1$
- MIPS supports
  - 2's complement integers
  - Unsigned integers
  - Floating point
- Again, **tradeoffs** are involved
  - What data types should be supported and what should not be?

# Data Type Tradeoffs

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- What is the benefit of **having more or high-level data types** in the ISA?
- What is the disadvantage?
- Think compiler/programmer vs. microarchitect
- Concept of **semantic gap**
  - Data types coupled tightly to the semantic level, or complexity of instructions → how close are instrs. to high-level languages
- Example: Early RISC architectures vs. Intel 432
  - Early RISC machines: Only integer data type
  - Intel 432: Object data type, capability based machine
  - VAX: Complex types, e.g., doubly-linked list

# Aside: An Example: **Binary**Coded**D**ecimal

- Each decimal digit is encoded with a fixed number of bits



"Binary clock" on the English Wikipedia.

[http://commons.wikimedia.org/wiki/File:Binary\\_clock.svg#mediaviewer/File:Binary\\_clock.svg](http://commons.wikimedia.org/wiki/File:Binary_clock.svg#mediaviewer/File:Binary_clock.svg)

"Digital-BCD-clock" by Julu - Own work. Licensed under Public Domain via Wikimedia Commons - <http://commons.wikimedia.org/wiki/File:Digital-BCD-clock.jpg#mediaviewer/File:Digital-BCD-clock.jpg>

# Addressing Modes

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- An addressing mode is a mechanism for specifying where an operand is located
- There are five addressing modes in LC-3
  - Immediate or literal (constant)
    - The operand is in some bits of the instruction
  - Register
    - The operand is in one of R0 to R7 registers
  - Three memory addressing modes
    - PC-relative
    - Indirect
    - Base+offset
- MIPS has pseudo-direct addressing (for j and jal), additionally, but does **not** have indirect addressing

# Why Have Different Addressing Modes?

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- Another example of programmer vs. microarchitect tradeoff
- **Advantage of more addressing modes:**
  - Enables better mapping of high-level programming constructs to hardware
    - some accesses are better expressed with a different mode → reduced number of instructions and code size
      - Array indexing
      - Pointer-based accesses (indirection)
      - Sparse matrix accesses
- **Disadvantages:**
  - More work for the compiler
  - More work for the microarchitect



# Many Tradeoffs in ISA Design...

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- Execution model – sequencing model and processing style
- Instruction length
- Instruction format
- Instruction types
- Instruction complexity vs. simplicity
- Data types
- Number of registers
- Addressing mode types
- Memory organization (address space, addressability, endianness, ...)
- Memory access restrictions and permissions
- Support for multiple instructions to execute in parallel?
- ...

# Operate Instructions

# Operate Instructions

---

- In **LC-3**, there are three operate instructions
  - NOT is a **unary operation** (one source operand)
    - It executes bitwise NOT
  - ADD and AND are **binary operations** (two source operands)
    - ADD is 2's complement addition
    - AND is bitwise SR1 & SR2
- In **MIPS**, there are many more
  - Most of **R-type** instructions (they are **binary operations**)
    - E.g., add, and, nor, xor...
  - **I-type** versions (i.e., with one immediate operand) of the R-type operate instructions
  - **F-type** operations, i.e., floating-point operations

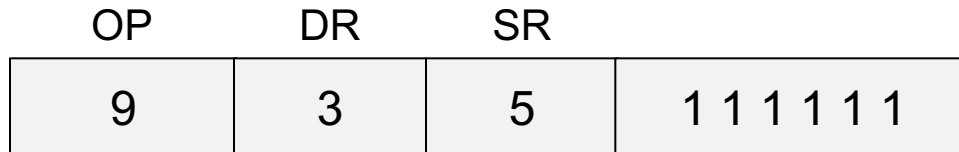
# NOT in LC-3

## NOT assembly and machine code

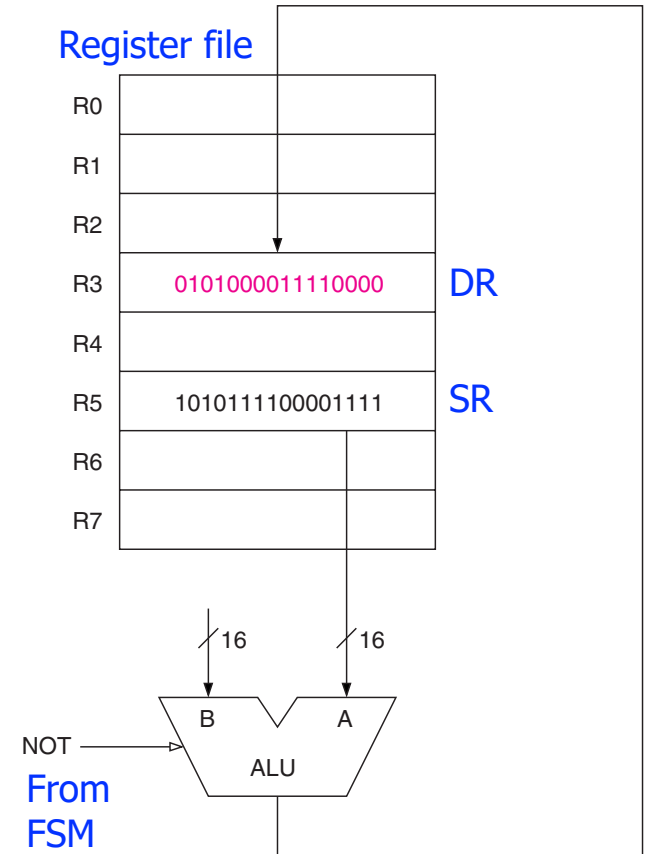
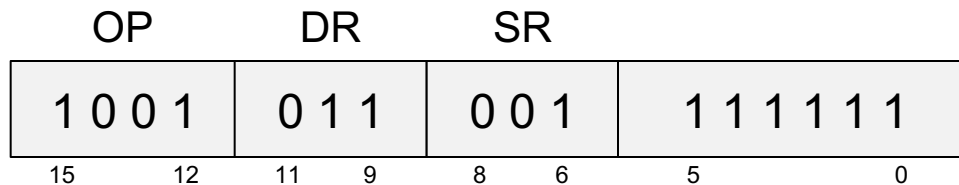
LC-3 assembly

```
NOT R3, R5
```

Field Values



Machine Code



There is **no NOT in MIPS**. How is it implemented?

# Operate Instructions

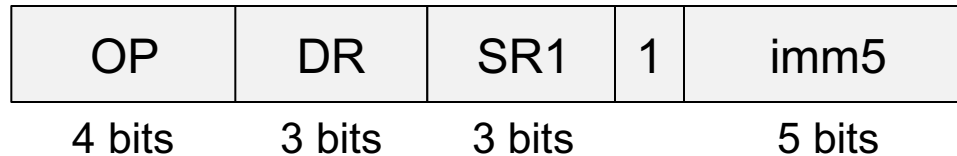
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- We are already familiar with LC-3's ADD and AND with register mode (R-type in MIPS)
- Now let us see the versions with one literal (i.e., immediate) operand
- **Subtraction** is another necessary operation
  - How is it implemented in LC-3 and MIPS?

# Operate Instr. with one Literal in LC-3

---

## ■ ADD and AND



- OP = operation
  - E.g., **ADD** = **0001** (same OP as the register-mode ADD)
    - **DR** ← **SR1** + **sign-extend(imm5)**
  - E.g., **AND** = **0101** (same OP as the register-mode AND)
    - **DR** ← **SR1** **AND** **sign-extend(imm5)**
- SR1 = source register
- DR = destination register
- **imm5** = Literal or immediate (sign-extend to 16 bits)

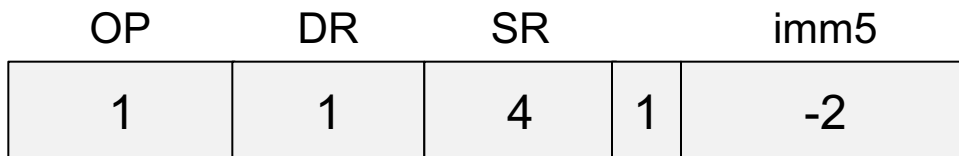
# ADD with one Literal in LC-3

## ADD assembly and machine code

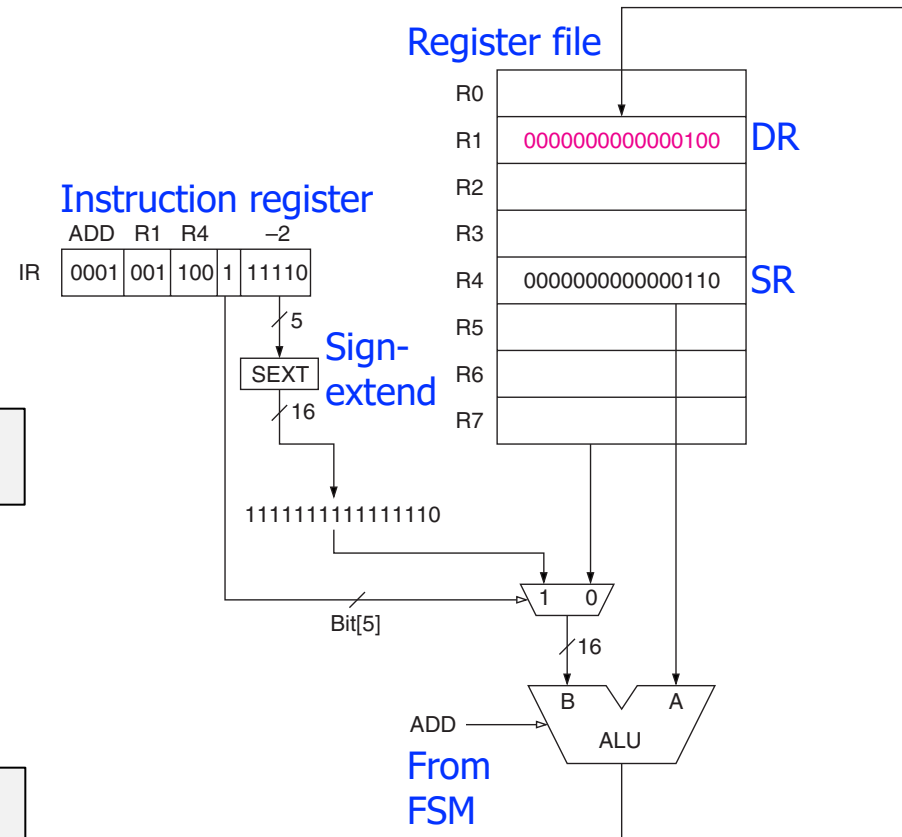
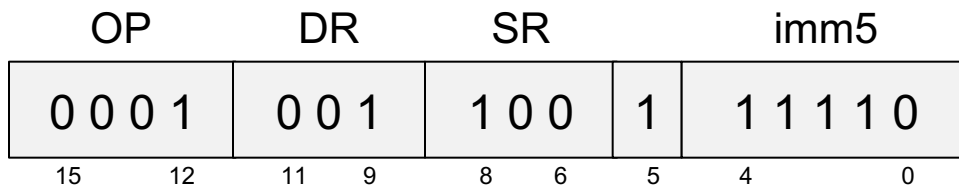
LC-3 assembly

```
ADD R1, R4, #-2
```

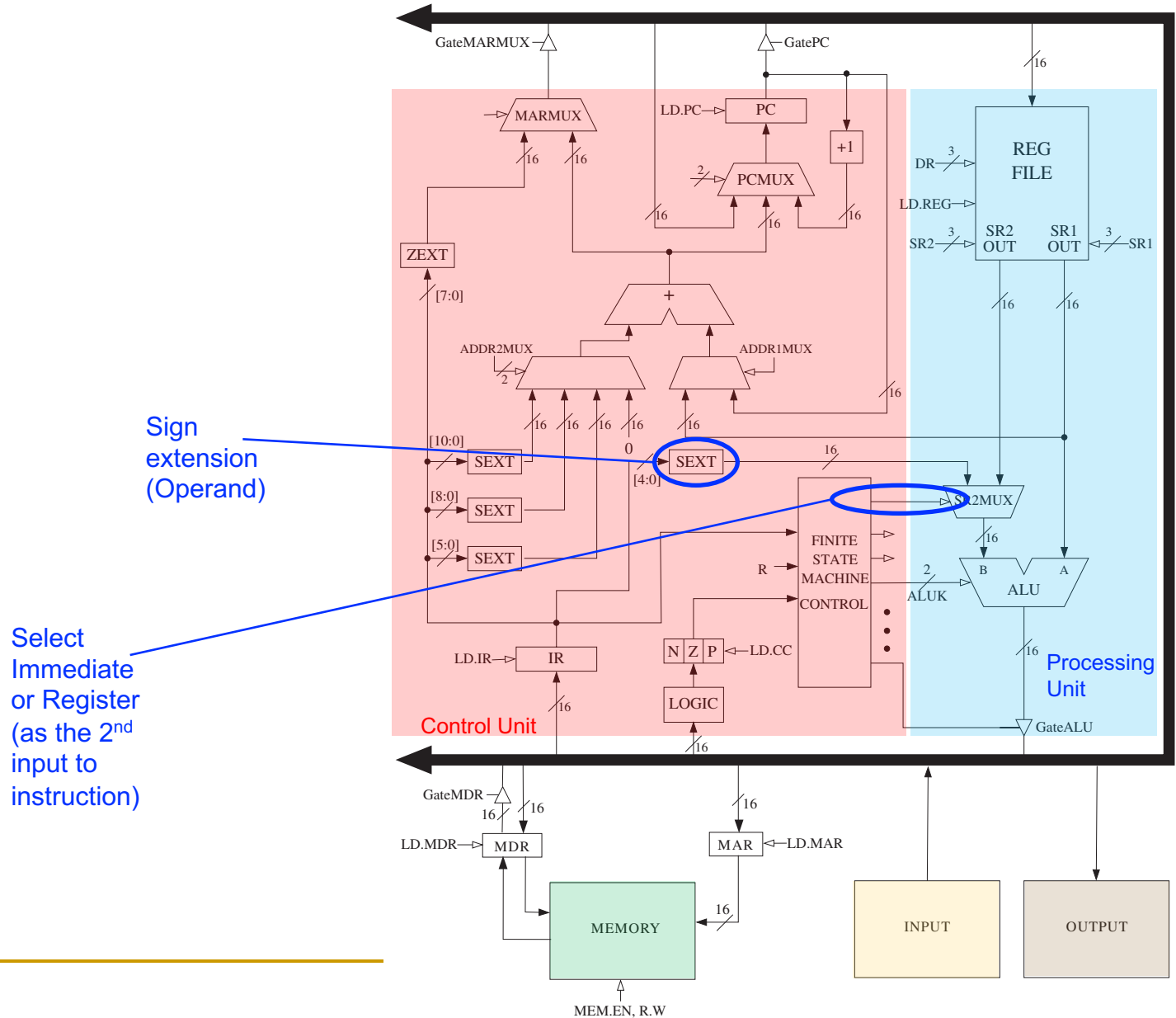
Field Values



Machine Code



# ADD with one Literal in LC-3 Data Path

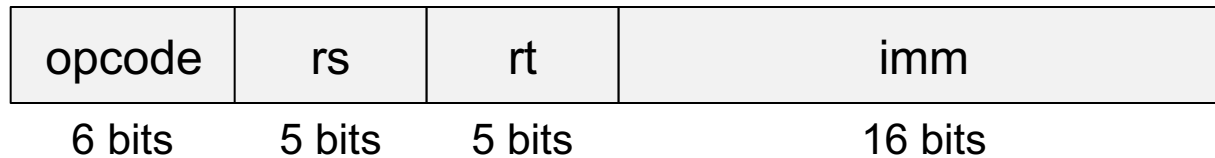




# Instructions with one Literal in MIPS

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- I-type MIPS Instructions
  - 2 register operands and immediate
- Some operate and data movement instructions



- opcode = operation
- rs = source register
- rt =
  - destination register in some instructions (e.g., `addi`, `lw`)
  - source register in others (e.g., `sw`)
- imm = Literal or immediate

# Add with one Literal in MIPS

---

- Add immediate

MIPS assembly

```
addi $s0, $s1, 5
```

Field Values

op	rs	rt	imm
0	17	16	5

$rt \leftarrow rs + \text{sign-extend}(\text{imm})$

Machine Code

op	rs	rt	imm
001000	10001	10010	0000 0000 0000 0101

0x22300005

# Subtract in LC-3

## ■ MIPS assembly

High-level code

```
a = b + c - d;
```

MIPS assembly

```
add $t0, $s0, $s1  
sub $s3, $t0, $s2
```

## ■ LC-3 assembly

High-level code

```
a = b + c - d;
```

LC-3 assembly

```
ADD R2, R0, R1  
NOT R4, R3  
ADD R5, R4, #1  
ADD R6, R2, R5
```

2's complement of R3

## ■ Tradeoff in LC-3

- More instructions
- But, simpler control logic

# Subtract Immediate

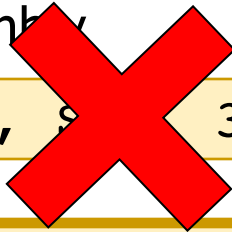
- MIPS assembly

High-level code

```
a = b - 3;
```

MIPS assembly

```
subi $s1, $s0, 3
```



Is **subi** necessary in MIPS?

MIPS assembly

```
addi $s1, $s0, -3
```

- LC-3

High-level code

```
a = b - 3;
```

LC-3 assembly

```
ADD R1, R0, #-3
```

# Data Movement Instructions and Addressing Modes

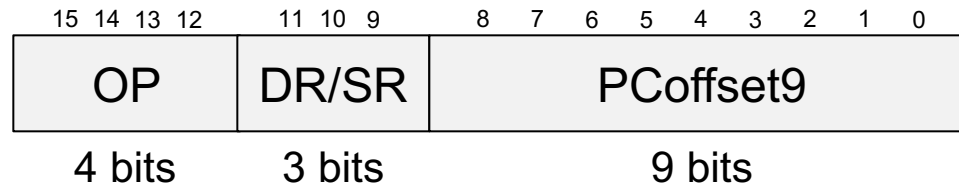
# Data Movement Instructions

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- In **LC-3**, there are seven data movement instructions
  - LD, LDR, LDI, LEA, ST, STR, STI
- Format of load and store instructions
  - Opcode (bits [15:12])
  - DR or SR (bits [11:9])
  - Address generation bits (bits [8:0])
  - Four ways to interpret bits, called **addressing modes**
    - PC-Relative Mode
    - Indirect Mode
    - Base+Offset Mode
    - Immediate Mode
- In **MIPS**, there are only **Base+offset** and **immediate modes** for load and store instructions

# PC-Relative Addressing Mode

## ■ LD (Load) and ST (Store)



- OP = opcode
  - E.g., LD = 0010
  - E.g., ST = 0011
- DR = destination register in LD
- SR = source register in ST
- LD:  $DR \leftarrow \text{Memory}[PC^\dagger + \text{sign-extend}(\text{PCOffset9})]$
- ST:  $\text{Memory}[PC^\dagger + \text{sign-extend}(\text{PCOffset9})] \leftarrow SR$

<sup>†</sup> This is the incremented PC

# LD in LC-3

## LD assembly and machine code

LC-3 assembly

LD R2, 0x1AF

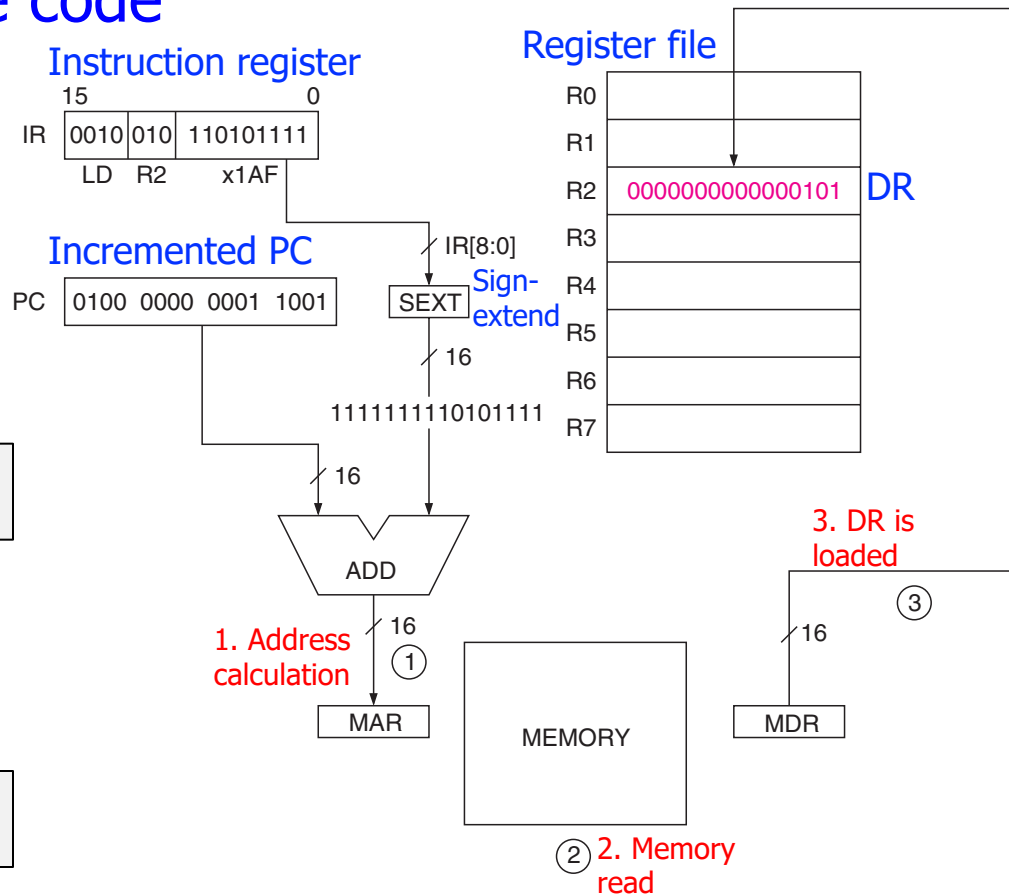
Field Values

OP	DR	PCoffset9
2	2	0x1AF

Machine Code

OP	DR	PCoffset9
0010	010	110101111

15 12 11 9 8 0



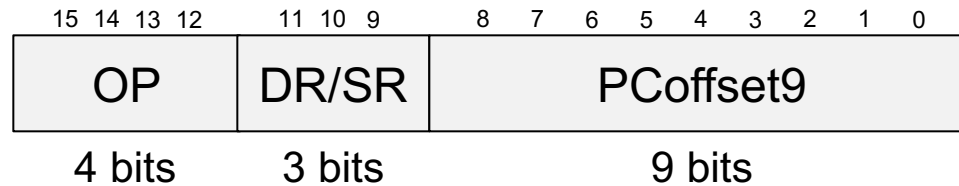
The memory address is **only +255 to -256** locations away of the **LD or ST instruction**

**Limitation:** The **PC-relative addressing mode** cannot address far away from the instruction



# Indirect Addressing Mode

- LDI (Load Indirect) and STI (Store Indirect)



- OP = opcode
  - E.g., LDI = 1010
  - E.g., STI = 1011
- DR = destination register in LDI
- SR = source register in STI
- LDI:  $DR \leftarrow \text{Memory}[\text{Memory}[\text{PC}^\dagger + \text{sign-extend}(\text{PCoffset9})]]$
- STI:  $\text{Memory}[\text{Memory}[\text{PC}^\dagger + \text{sign-extend}(\text{PCoffset9})]] \leftarrow SR$

<sup>†</sup> This is the incremented PC

# LDI in LC-3

## LDI assembly and machine code

LC-3 assembly

LDI R3, 0x1CC

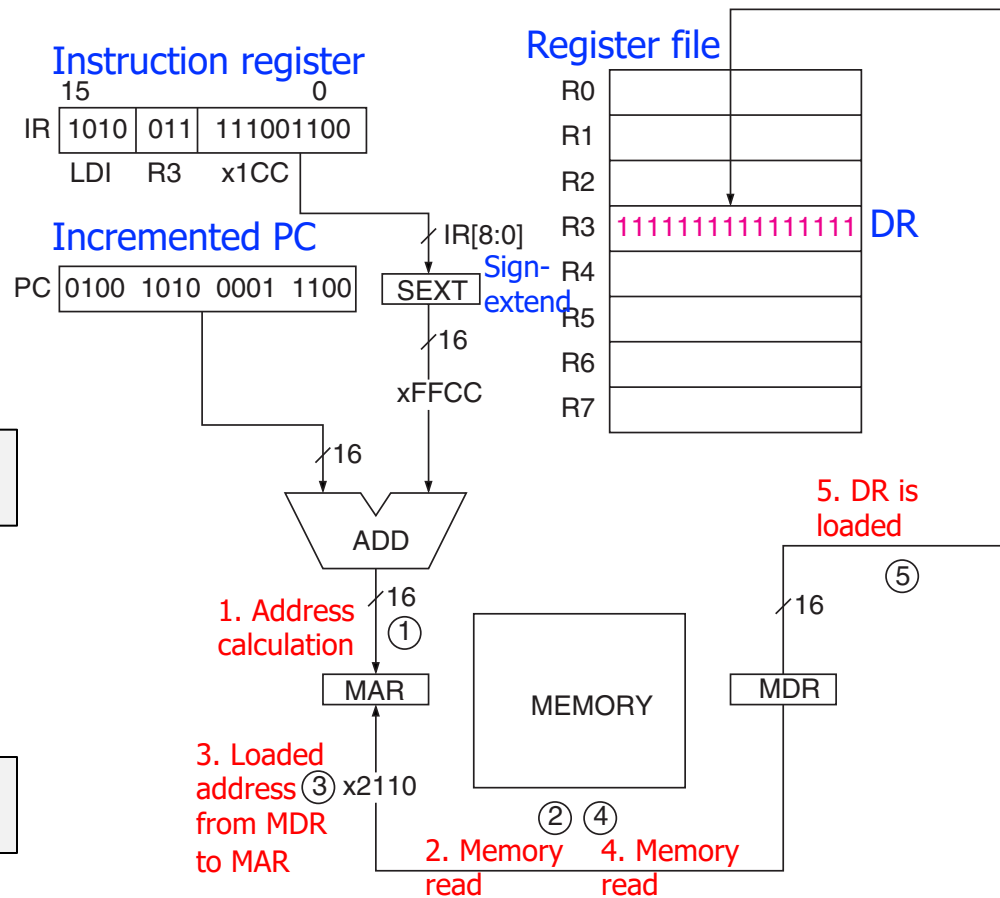
Field Values

OP	DR	PCoffset9
A	3	0x1CC

Machine Code

OP	DR	PCoffset9
1010	011	111001100

15 12 11 9 8 0

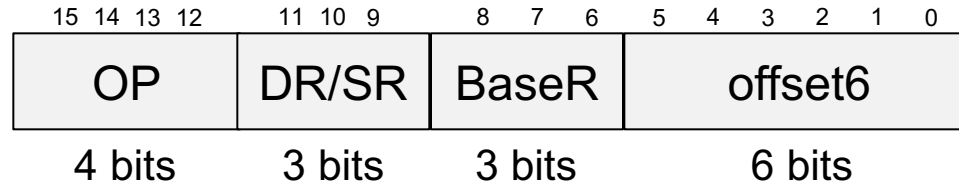


Now the address of the operand can be anywhere in the memory

# Base+Offset Addressing Mode

---

- LDR (Load Register) and STR (Store Register)



- OP = opcode
  - E.g., LDR = 0110
  - E.g., STR = 0111
- DR = destination register in LDR
- SR = source register in STR
- LDR:  $DR \leftarrow \text{Memory}[\text{BaseR} + \text{sign-extend}(\text{offset6})]$
- STR:  $\text{Memory}[\text{BaseR} + \text{sign-extend}(\text{offset6})] \leftarrow SR$

# LDR in LC-3

## LDR assembly and machine code

LC-3 assembly

LDR R1, R2, 0x1D

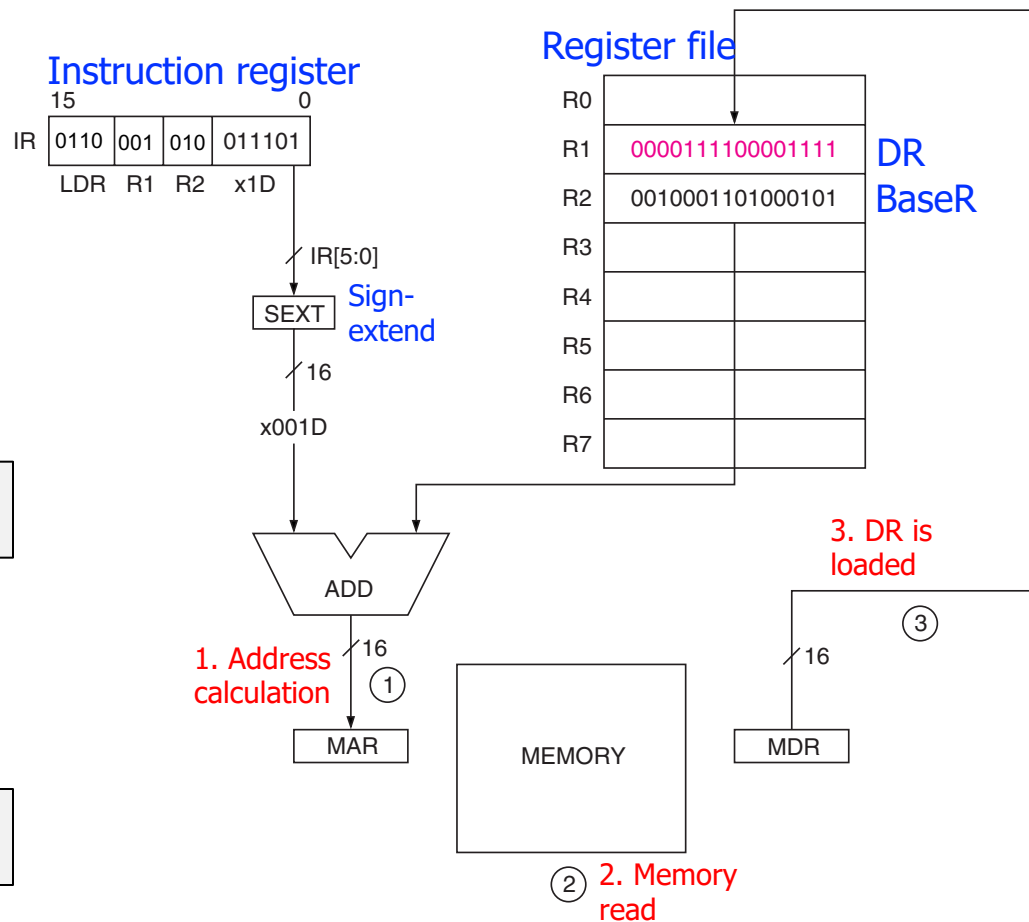
Field Values

OP	DR	BaseR	offset6
6	1	2	0x1D

Machine Code

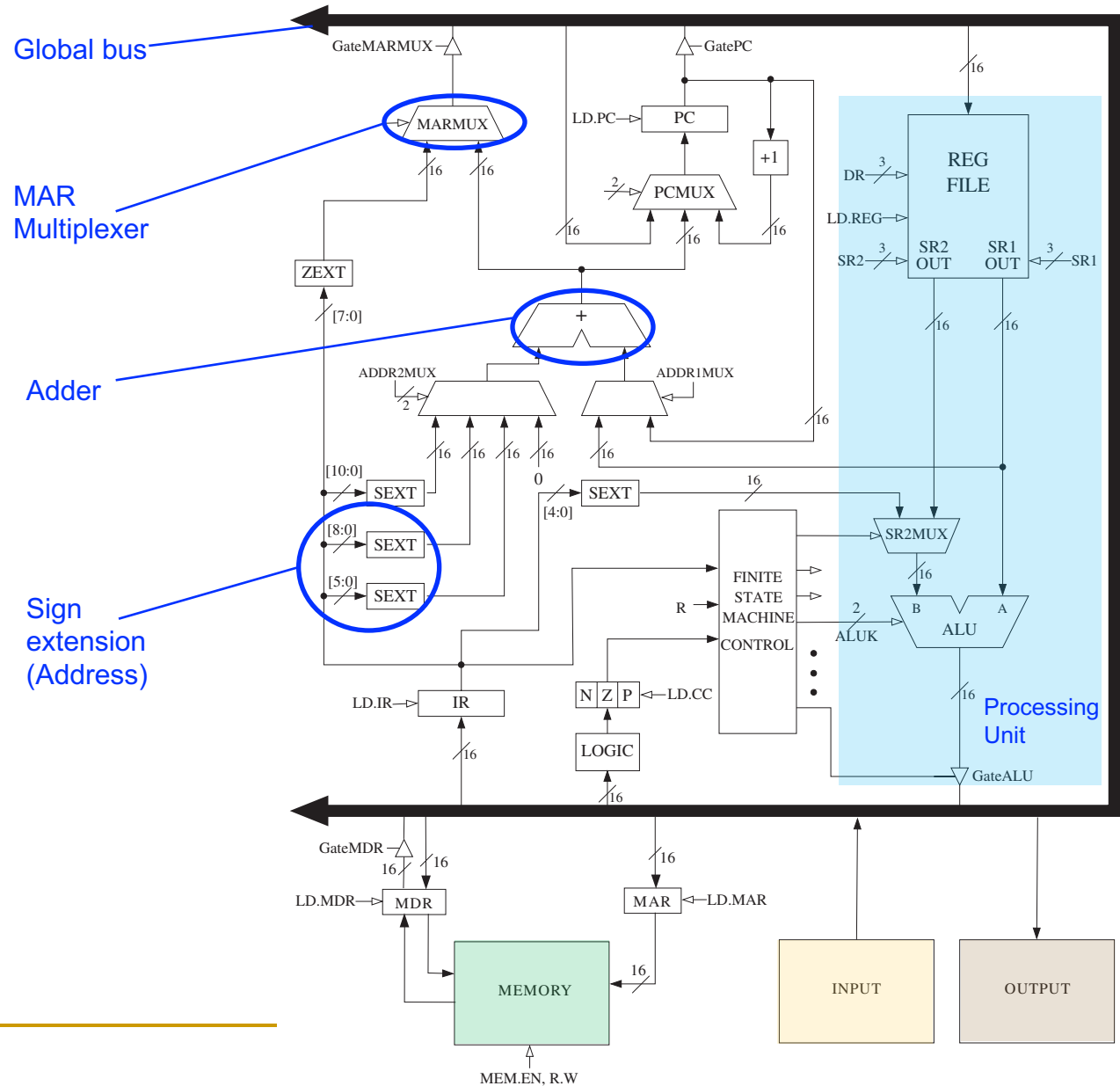
OP	DR	BaseR	offset6
0110	001	010	011101

15 12 11 9 8 6 5 0



Again, the address of the operand can be anywhere in the memory

# Address Calculation in LC-3 Data Path



# Base+Offset Addressing Mode in MIPS

- In MIPS, `lw` and `sw` use base+offset mode (or **base addressing mode**)

High-level code

```
A[2] = a;
```

MIPS assembly

```
sw    $s3, 8($s0)
```

**Memory[\$s0 + 8] ← \$s3**

Field Values

op	rs	rt	imm
43	16	19	8

- `imm` is the 16-bit offset, which is **sign-extended to 32 bits**

# An Example Program in MIPS and LC-3

---

## High-level code

```
a    = A[0];  
c    = a + b - 5;  
B[0] = c;
```

## MIPS registers

```
A = $s0  
b = $s2  
B = $s1
```

## LC-3 registers

```
A = R0  
b = R2  
B = R1
```

## MIPS assembly

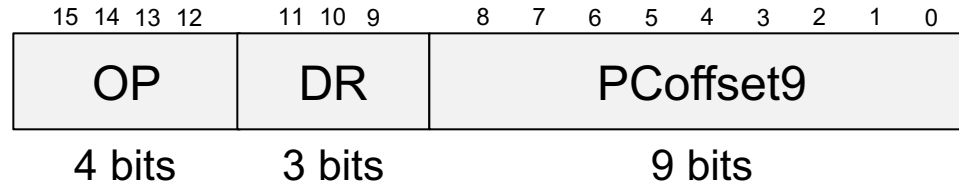
```
lw    $t0, 0($s0)  
add   $t1, $t0, $s2  
addi  $t2, $t1, -5  
sw    $t2, 0($s1)
```

## LC-3 assembly

```
LDR   R5, R0, #0  
ADD   R6, R5, R2  
ADD   R7, R6, #-5  
STR   R7, R1, #0
```

# Immediate Addressing Mode

## ■ LEA (Load Effective Address)



- OP = 1110
- DR = destination register
- LEA:  $DR \leftarrow PC^\dagger + \text{sign-extend}(\text{PCoffset9})$

What is the **difference from PC-Relative** addressing mode?

Answer: Instructions with **PC-Relative** mode **load from memory**, but **LEA does not** → Hence the name *Load Effective Address*

<sup>†</sup> This is the incremented PC



# LEA in LC-3

## LEA assembly and machine code

LC-3 assembly

```
LEA R5, #-3
```

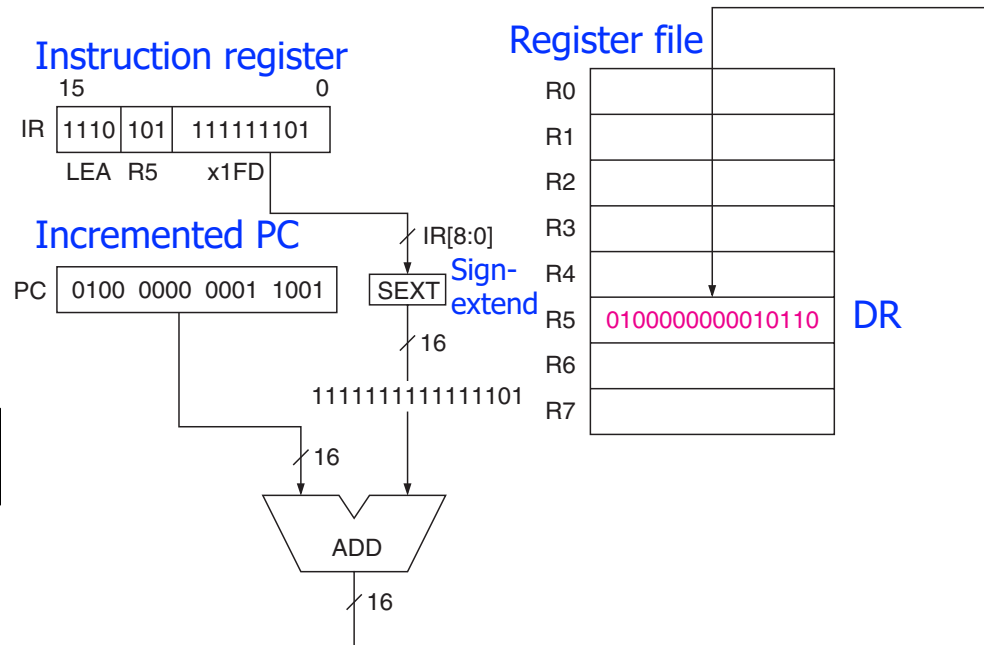
Field Values

OP	DR	PCoffset9
E	5	0x1FD

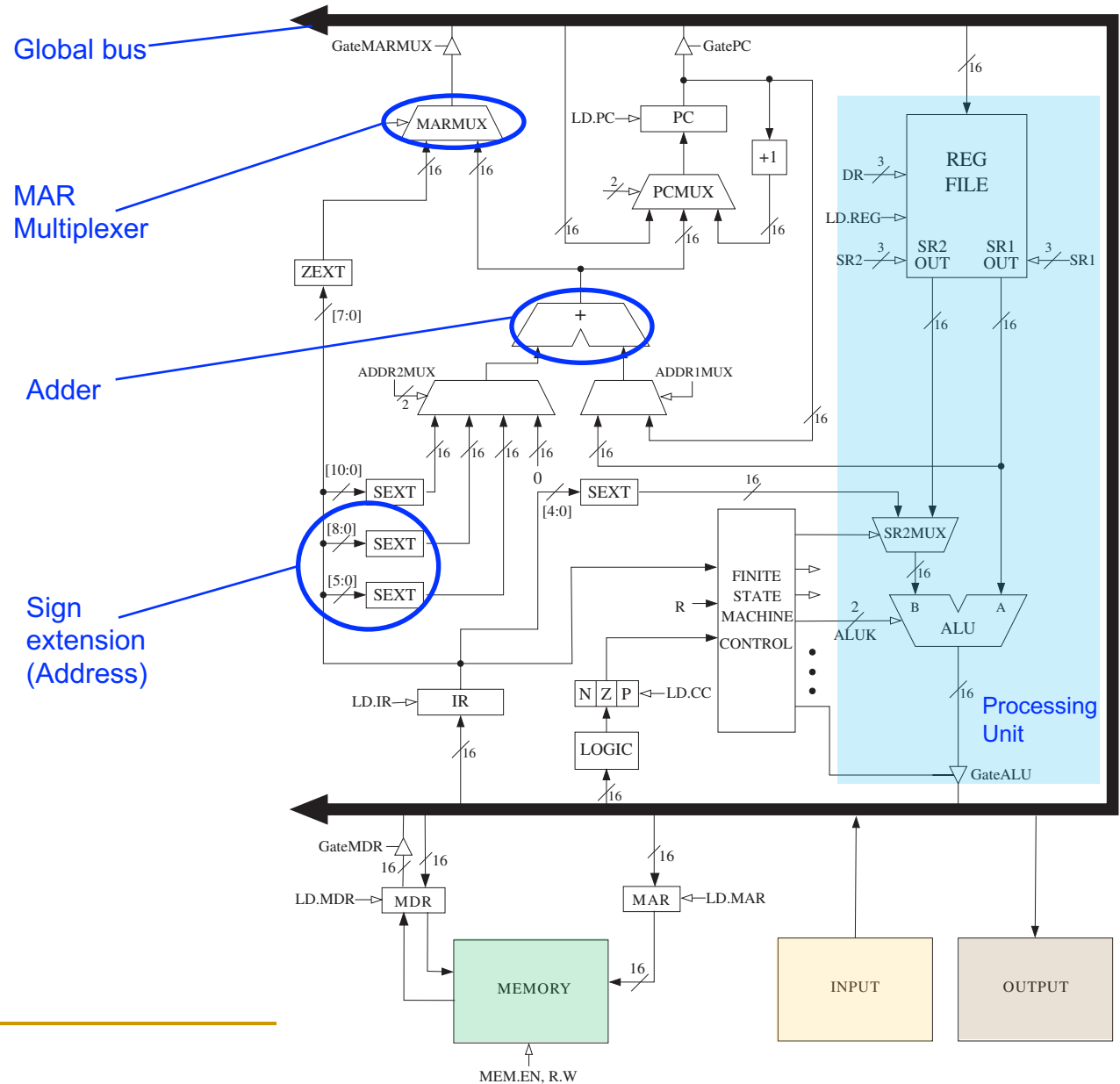
Machine Code

OP	DR	PCoffset9
1 1 1 0	1 0 1	1 1 1 1 1 1 1 0 1

15 12 11 9 8 0



# Address Calculation in LC-3 Data Path



# Immediate Addressing Mode in MIPS

---

- In MIPS, `lui` (load upper immediate) loads a 16-bit immediate into the upper half of a register and sets the lower half to 0
- It is used to assign 32-bit constants to a register

High-level code

```
a = 0x6d5e4f3c;
```

MIPS assembly

```
# $s0 = a  
lui   $s0, 0x6d5e  
ori   $s0, 0x4f3c
```

# Addressing Example in LC-3

- What is the final value of R3?

P&P, Chapter 5.3.5

Address	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
x30F6	1	1	1	0	0	0	1	1	1	1	1	1	1	1	0	1	<b>R1 ← PC - 3</b>
x30F7	0	0	0	1	0	1	0	0	0	1	1	0	1	1	1	0	<b>R2 ← R1 + 14</b>
x30F8	0	0	1	1	0	1	0	1	1	1	1	1	1	0	1	1	<b>M[x30F4] ← R2</b>
x30F9	0	1	0	1	0	1	0	0	1	0	1	0	0	0	0	0	<b>R2 ← 0</b>
x30FA	0	0	0	1	0	1	0	0	1	0	1	0	0	1	0	1	<b>R2 ← R2 + 5</b>
x30FB	0	1	1	1	0	1	0	0	0	1	0	0	1	1	1	0	<b>M[R1 + 14] ← R2</b>
x30FC	1	0	1	0	0	1	1	1	1	1	1	1	0	1	1	1	<b>R3 ← M[M[x30F4]]</b>

# Addressing Example in LC-3

- What is the final value of R3?

P&P, Chapter 5.3.5

Address	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
x30F6	1	1	0	0	0	1	3	1	1	1	1	1	1	1	1	0	R1 = PC - 3 = 0x30F7 - 3 = 0x30F4
x30F7	0	0	1	0	1	0	0	0	1	1	0	1	1	0	1	0	R2 = R1 + 14 = 0x30F4 + 14 = 0x3102
x30F8	0	1	1	0	1	0	5	1	1	1	1	1	0	1	0	1	M[PC - 5] = M[0x030F4] = 0x3102
x30F9	1	0	1	0	1	0	0	1	0	1	0	0	0	0	0	0	R2 = 0
x30FA	0	0	1	0	1	0	0	1	0	1	5	0	1	0	1	0	R2 = R2 + 5 = 5
x30FB	1	1	1	0	1	0	0	0	1	0	0	0	0	0	0	0	M[R1 + 14] = M[0x30F4 + 14] = M[0x3102] = 5
x30FC	0	1	0	0	1	1	9	1	1	1	1	1	1	1	1	1	R3 = M[M[PC - 9]] = M[M[0x30FD - 9]] = M[M[0x30F4]] = M[0x3102] = 5

- The final value of R3 is 5

# Control Flow Instructions

# Control Flow Instructions

---

- Allow a program to execute **out of sequence**
- Conditional branches and unconditional jumps
  - **Conditional branches** are used to **make decisions**
    - E.g., if-else statement
  - In LC-3, three **condition codes** are used
  - **Jumps** are used to implement
    - **Loops**
    - **Function calls**
  - **JMP** in LC-3 and **j** in MIPS

# Condition Codes in LC-3

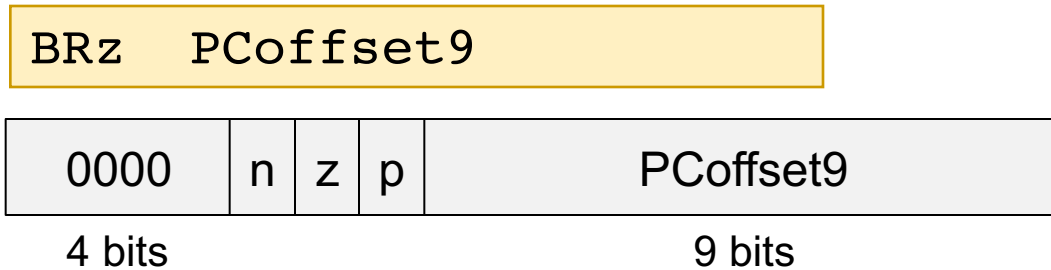
---

- Each time one GPR (R0-R7) is written, **three single-bit registers** are updated
- Each of these **condition codes** are either set (set to 1) or cleared (set to 0)
  - If the written value is **negative**
    - **N** is set, Z and P are cleared
  - If the written value is **zero**
    - **Z** is set, N and P are cleared
  - If the written value is **positive**
    - **P** is set, N and Z are cleared
- x86 and SPARC are examples of ISAs that use condition codes



# Conditional Branches in LC-3

## ■ BRz (Branch if Zero)



- $n, z, p =$  **which condition code is tested** (N, Z, and/or P)
  - $n, z, p$ : instruction bits to identify the condition codes to be tested
  - $N, Z, P$ : values of the corresponding condition codes
- $PCoffset9 =$  immediate or constant value
- **if  $((n \text{ AND } N) \text{ OR } (p \text{ AND } P) \text{ OR } (z \text{ AND } Z))$** 
  - **then  $PC \leftarrow PC^\dagger + \text{sign-extend}(PCoffset9)$**
- Variations: BRn, BRz, BRp, BRzp, BRnp, BRnz, BRnzp

<sup>†</sup> This is the incremented PC

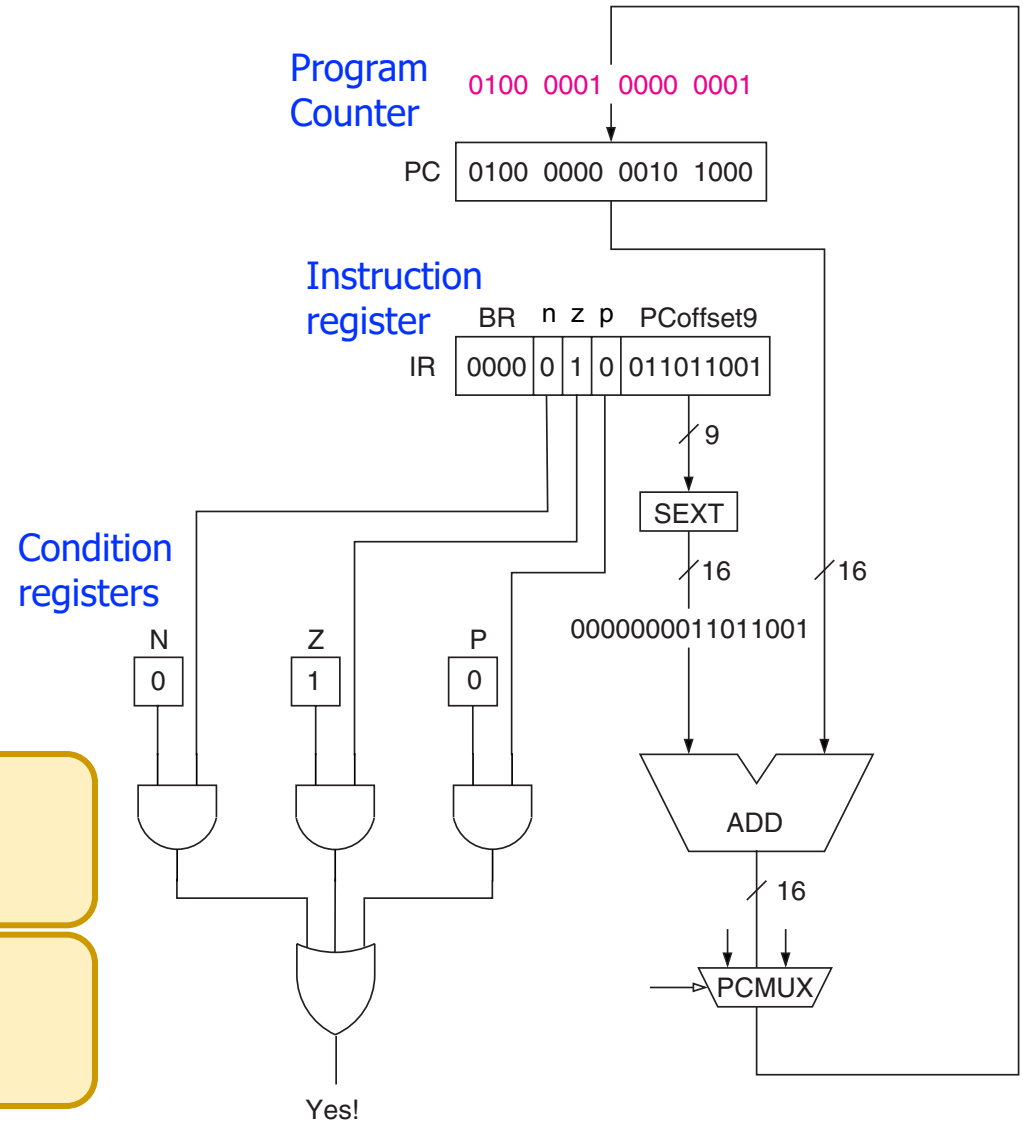
# Conditional Branches in LC-3

## BRz

BRz 0x0D9

What if  $n = z = p = 1$ ?\*  
(i.e., BRnzp)

And what if  $n = z = p = 0$ ?

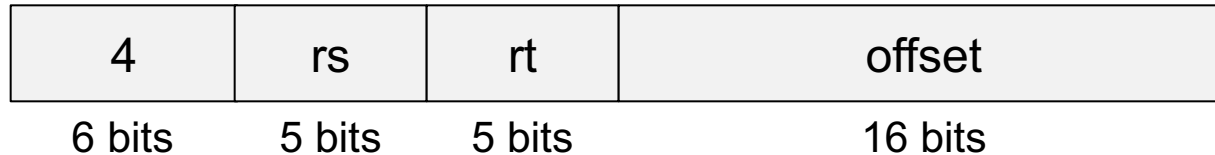


\*n, z, p are the instruction bits to identify the condition codes to be tested

# Conditional Branches in MIPS

## ■ beq (Branch if Equal)

```
beq $s0, $s1, offset
```



- 4 = opcode
- rs, rt = source registers
- offset = immediate or constant value
- if  $rs == rt$ 
  - then  $PC \leftarrow PC^{\dagger} + \text{sign-extend}(\text{offset}) * 4$
- Variations: beq, bne, blez, bgtz

<sup>†</sup> This is the incremented PC

# Branch If Equal in MIPS and LC-3

---

## MIPS assembly

```
beq $s0, $s1, offset
```

## LC-3 assembly

```
NOT R2, R1
```

```
ADD R3, R2, #1
```

```
ADD R4, R3, R0
```

```
BRz offset
```

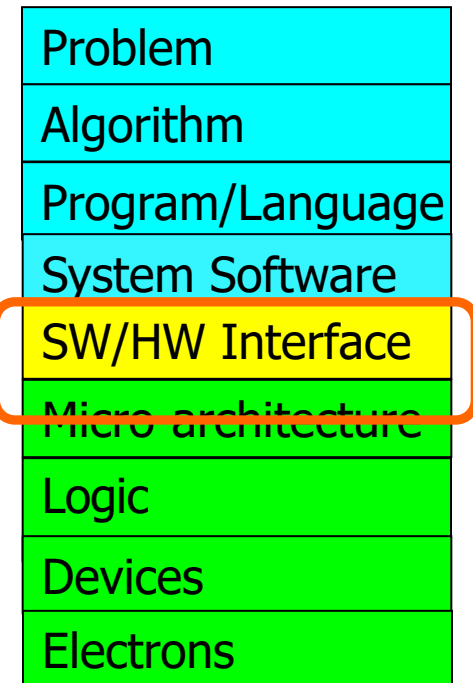
Subtract  
(R0 - R1)

- This is an example of **tradeoff** in the instruction set
  - The same functionality requires **more instructions in LC-3**
  - But, the **control logic** requires **more complexity in MIPS**

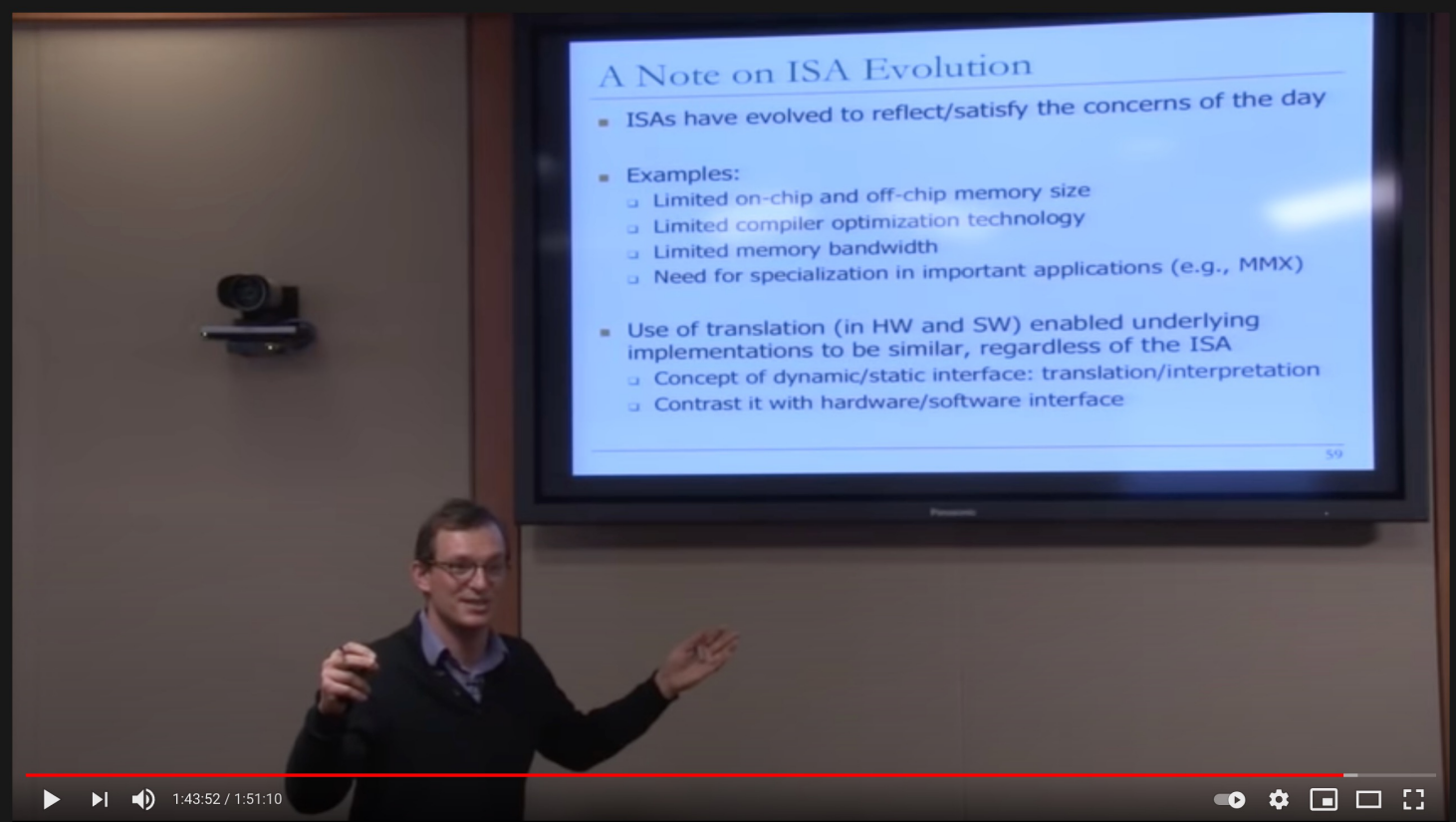
# What We Learned

---

- Basic elements of a computer & **the von Neumann model**
  - LC-3: An example von Neumann machine
- **Instruction Set Architectures: LC-3 and MIPS**
  - Operate instructions
  - Data movement instructions
  - Control instructions
- **Instruction formats**
- **Addressing modes**



# There Is A Lot More to Cover on ISAs



**A Note on ISA Evolution**

- ISAs have evolved to reflect/satisfy the concerns of the day
- Examples:
  - Limited on-chip and off-chip memory size
  - Limited compiler optimization technology
  - Limited memory bandwidth
  - Need for specialization in important applications (e.g., MMX)
- Use of translation (in HW and SW) enabled underlying implementations to be similar, regardless of the ISA
  - Concept of dynamic/static interface: translation/interpretation
  - Contrast it with hardware/software interface

59

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Lecturer: Prof. Onur Mutlu (<http://users.ece.cmu.edu/~omutlu/>)  
Date: Jan 16th, 2015

# Many Different ISAs Over Decades

---

- x86
- PDP-x: Programmed Data Processor (PDP-11)
- VAX
- IBM 360
- CDC 6600
- SIMD ISAs: CRAY-1, Connection Machine
- VLIW ISAs: Multiflow, Cydrome, IA-64 (EPIC)
- PowerPC, POWER
- RISC ISAs: Alpha, MIPS, SPARC, ARM, RISC-V, ...
  
- What are the fundamental differences?
  - E.g., how instructions are specified and what they do
  - E.g., how complex are the instructions

# Complex vs. Simple Instructions

---

- **Complex instruction:** An instruction **does a lot of work**, e.g. many operations
  - ❑ Insert in a doubly linked list
  - ❑ Compute FFT
  - ❑ String copy
  - ❑ ...
- **Simple instruction:** An instruction **does little work** -- it is a primitive using which complex operations can be built
  - ❑ Add
  - ❑ XOR
  - ❑ Multiply
  - ❑ ...



# Complex vs. Simple Instructions

---

## ■ Advantages of Complex instructions

- + **Denser encoding** → smaller code size → better memory utilization, saves off-chip bandwidth, better cache hit rate (better packing of instructions)
- + **Simpler compiler**: no need to optimize small instructions as much

## ■ Disadvantages of Complex Instructions

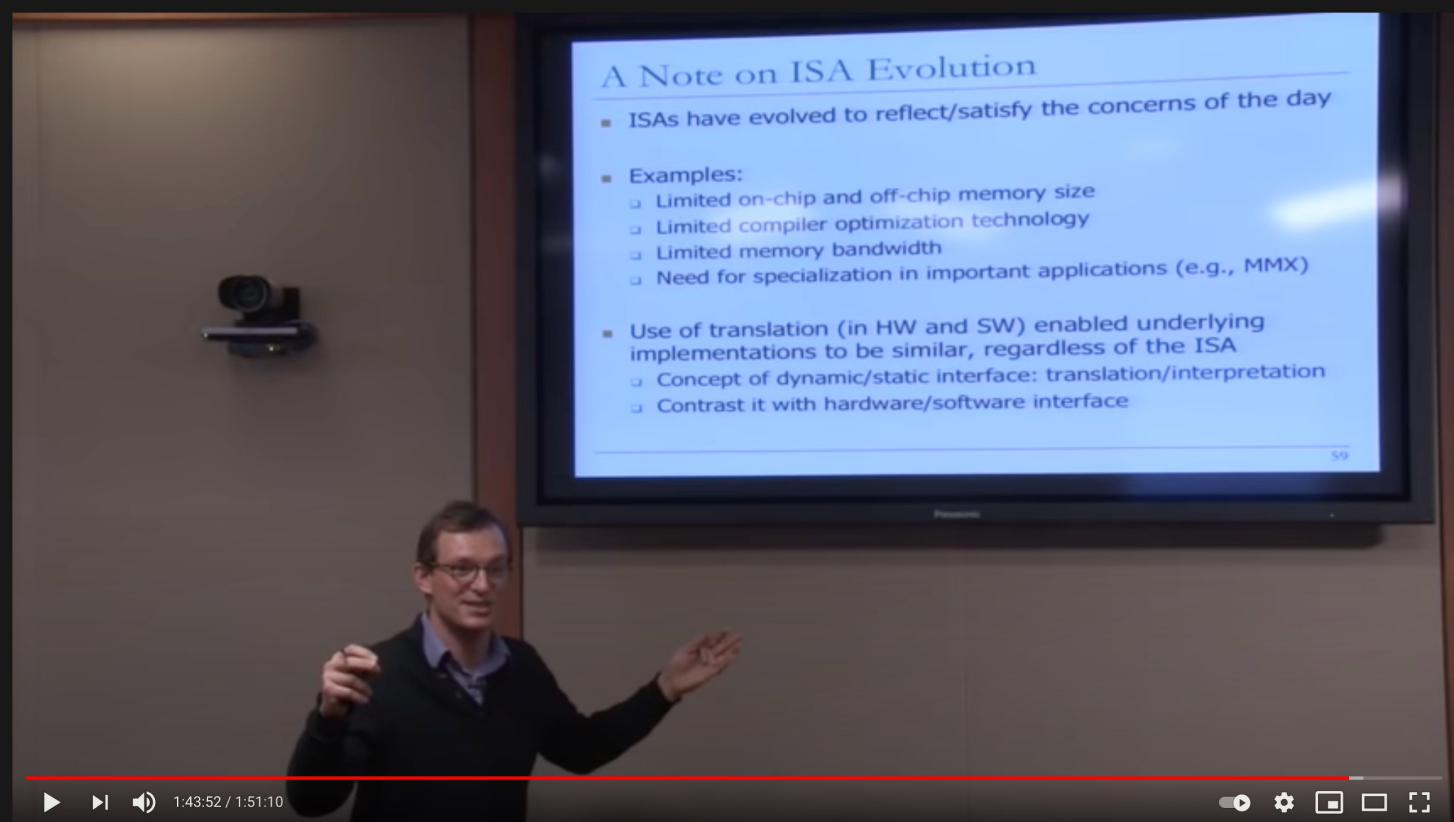
- **Larger chunks of work** → compiler has less opportunity to optimize (limited in fine-grained optimizations it can do)
- **More complex hardware** → translation from a high level to control signals and optimization needs to be done by hardware

# ISA-level Tradeoffs: Number of Registers

---

- Affects:
  - Number of bits used for encoding register address
  - Number of values kept in fast storage (register file)
  - (uarch) Size, access time, power consumption of register file
- Large number of registers:
  - + Enables better register allocation (and optimizations) by compiler → fewer saves/restores
  - Larger instruction size
  - Larger register file size

# There Is A Lot More to Cover on ISAs



**A Note on ISA Evolution**

- ISAs have evolved to reflect/satisfy the concerns of the day
- Examples:
  - Limited on-chip and off-chip memory size
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# There Is A Lot More to Cover on ISAs

## ISA-level Tradeoffs: Number of Registers

- Affects:
  - Number of bits used for encoding register address
  - Number of values kept in fast storage (register file)
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  - Larger instruction size
  - Larger register file size

12

25:29 / 1:30:28



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Lecture 4. ISA Tradeoffs (cont.) & MIPS ISA  
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Date: Jan 21th, 2015

<https://www.youtube.com/onurmutlulectures>

# Detailed Lectures on ISAs & ISA Tradeoffs

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## ■ Computer Architecture, Spring 2015, Lecture 3

- ISA Tradeoffs (CMU, Spring 2015)
- <https://www.youtube.com/watch?v=QKdiZSfwg-g&list=PL5PHm2jkkXmi5CxxI7b3JCL1TWybTDtKq&index=3>

## ■ Computer Architecture, Spring 2015, Lecture 4

- ISA Tradeoffs & MIPS ISA (CMU, Spring 2015)
- <https://www.youtube.com/watch?v=RBgeCCW5Hjs&list=PL5PHm2jkkXmi5CxxI7b3JCL1TWybTDtKq&index=4>

## ■ Computer Architecture, Spring 2015, Lecture 2

- Fundamental Concepts and ISA (CMU, Spring 2015)
- <https://www.youtube.com/watch?v=NpC39uS4K4o&list=PL5PHm2jkkXmi5CxxI7b3JCL1TWybTDtKq&index=2>

# Digital Design & Computer Arch.

## Lecture 10a: Instruction Set Architectures II

Prof. Onur Mutlu

ETH Zürich

Spring 2022

25 March 2022